

# THE GEOMETRICAL MULTISCALE MODELING IN HEMODYNAMICS

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MATEMÁTICA  
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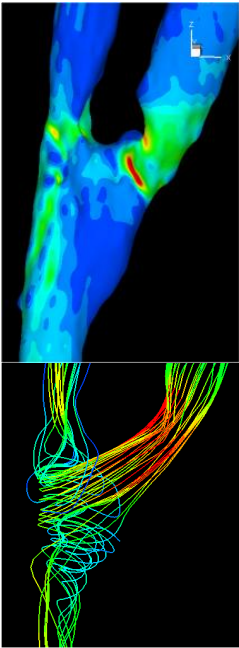
**ADÉLIA SEQUEIRA**

**Workshop on Nonlinear PDE's**

**Dedicated to 80th anniversary of birth of  
Prof. Jindřich Nečas**

**December 13-15, 2009**

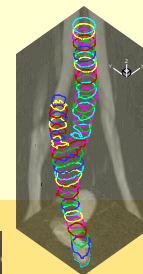
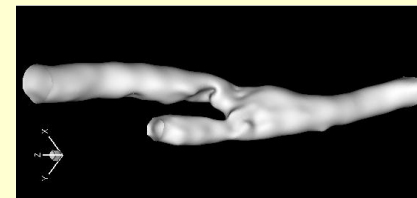
**Czech Academy of Sciences, Prague (Czech Republic)**



Patient's real data

Mathematical Models

Geometry reconstruction



**PROBLEM**  
Analysis of the cardiovascular system

PDEs Analysis

$$\int x(t) dt = \frac{x(t)}{dt} = k$$

$$\alpha - \frac{1}{\sqrt{2}} \frac{\partial u}{\partial t} + \frac{\partial^2 u}{\partial x^2}$$

$$v = \sqrt{\frac{g\lambda}{2\pi} + \frac{2\pi\gamma}{\rho\lambda}}$$

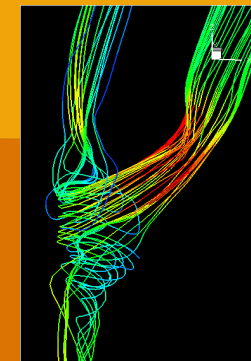
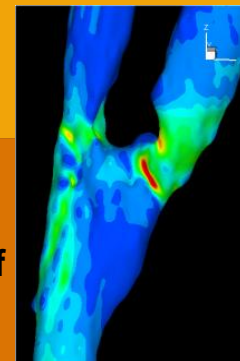
$$= \int_{-\infty}^{\infty} (\alpha(k) e^{i(kx - \omega t)}) dk$$

$$E = mc^2$$

Numerical Methods



Computer Simulations



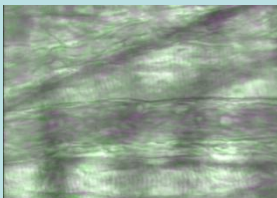
3D visualization of results

FEEDBACK

VALIDATION  
Comparison with experiments



Experimental Models



In vivo



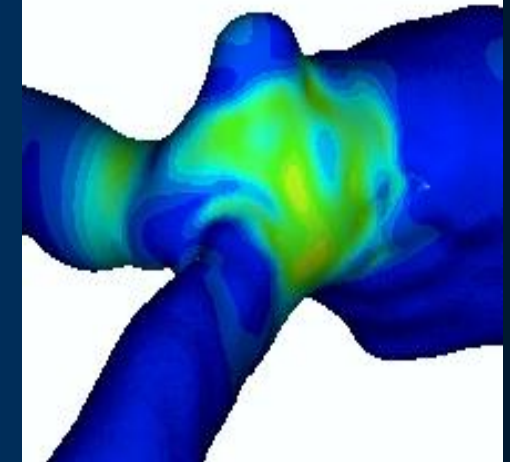
In vitro

Literature benchmark

# MOTIVATION

Hemodynamics vs cardiovascular diseases: local fluid patterns and **wall shear stress** are strictly related to the development of cardiovascular diseases (indicator of atherosclerosis)

$$WSS = \mu \left( \frac{\partial \mathbf{u}}{\partial \mathbf{n}} \cdot \boldsymbol{\tau} \right) \Big|_{wall}$$



WSS pulmonary artery  
(congenital heart disease)

## ➤ Difficulties in modeling blood flow

❖ **Blood Rheology**

❖ **Complex geometry** →

3D flow simulations are restricted to specific regions of interest

❖ **Closed system** →

Local flow dynamics has an important role in the systemic circulation (and vice-versa)

# MATHEMATICAL MODEL

1. Blood rheology
2. Fluid-structure interaction
3. Geometrical multiscale approach

# CIRCULATORY SYSTEM: FLUID DYNAMIC VALUES

Relationship between arterial size, number of vessels and average Reynolds numbers

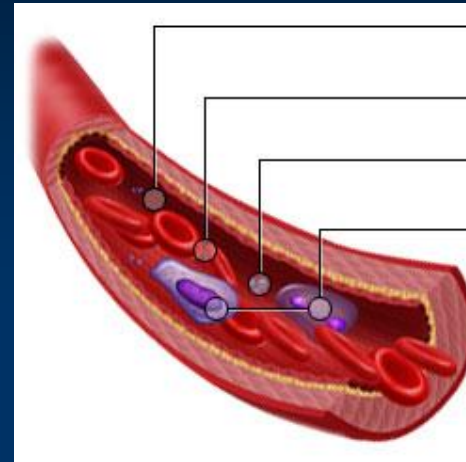
Vessel	Radius (cm)	Number	Wall thickness (cm)	Average Re number
Aorta	1.25	1	0.2	3400
Arteries	0.2	159	0.1	500
Arterioles	$1.5 \times 10^{-3}$	$5.7 \times 10^7$	$2 \times 10^{-3}$	0.7
Capillaries	$3 \times 10^{-4}$	$1.6 \times 10^{10}$	$1 \times 10^{-4}$	0.002
Venules	$1 \times 10^{-3}$	$1.3 \times 10^9$	$2 \times 10^{-4}$	0.01
Veins	0.25	200	0.05	140
Vena cava	1.5	1	0.15	3300

Turbulence can develop in a few cases:

High cardiac output (exercise); Stenoses; Low blood density (for example: anemia)

# BLOOD COMPOSITION

- Blood is a suspension of
  - cells
    - erythrocytes (RBCs)
    - leukocytes (WBCs)
    - platelets
  - plasma (90-92% water + proteins, organic salts)



Plasma  
 Red blood cells  
 Platelets  
 White blood cells

	Number/ mm <sup>3</sup>	Shape (unstressed)	Size μm (unstressed)	Volume Conc.
<b>erythrocytes</b>	4-6×10 <sup>6</sup>	Biconcave discs with no nuclei	8×1-3	45%
<b>leukocytes</b>	4-11 ×10 <sup>3</sup>	roughly spherical	7-22	1%
<b>platelets</b>	2.5-5 ×10 <sup>5</sup>	Rounded or oval discs	2-4	

# BLOOD RHEOLOGY

➤ Why is blood a non-Newtonian fluid ?

▶ Non-Constant Viscosity ◀

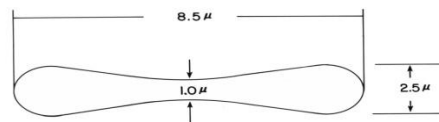
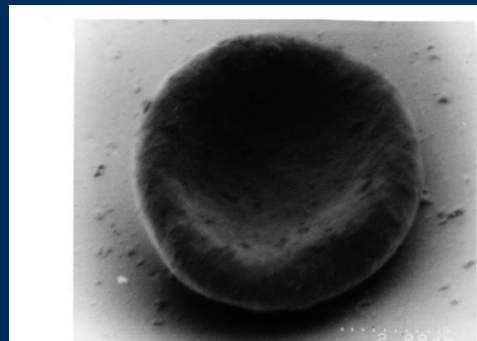
Main Factors:

RBC aggregation  
and  
deformability

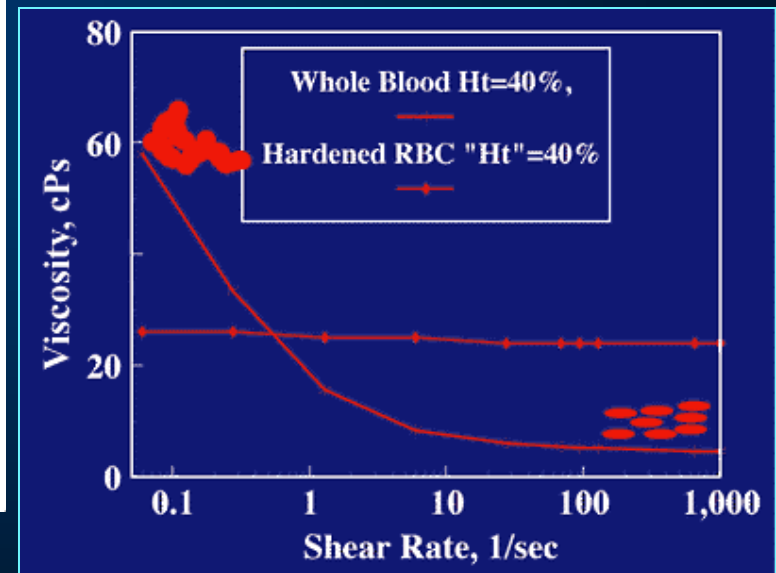
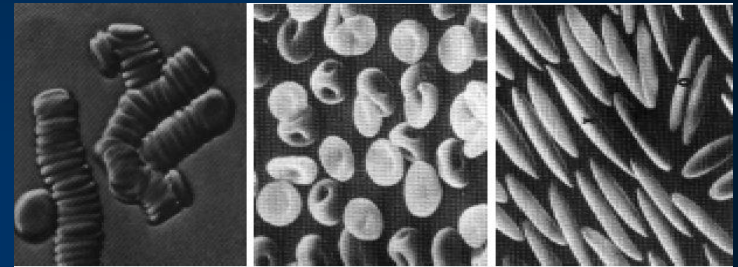
Other Factors

Hematocrit  
Osmotic Pressure  
Plasma Composition  
.....

Shear Thinning



Courtesy of Prof. K.B. Chandran, University of Iowa.



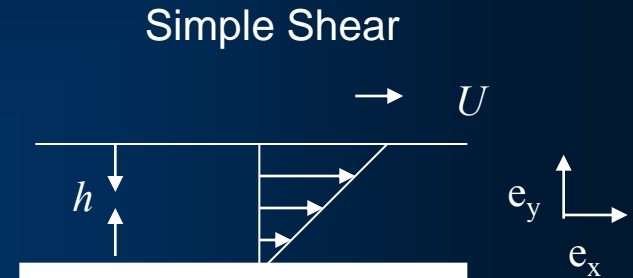
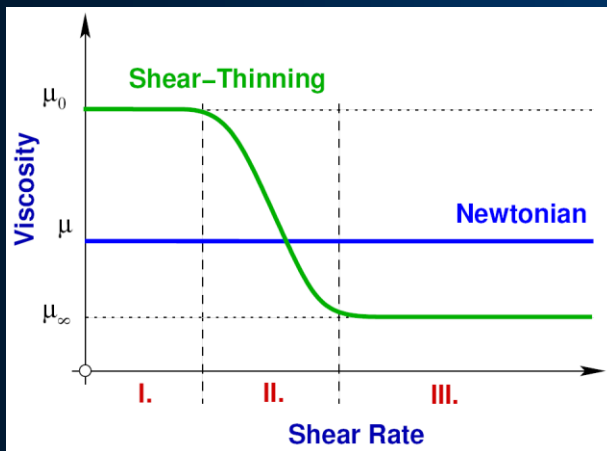


# NEWTONIAN vs NON-NEWTONIAN FLUID BEHAVIOR

## ◆ Non - Constant Viscosity

$$T = -pI + \tau = -pI + 2\mu(\dot{\gamma})D$$

- Shear thinning (or pseudoplastic) fluids
- Shear thickening (or dilatant) fluids
- Yield stress (Bingham plastic) fluids



$$\dot{\gamma} = U / h \quad \rightarrow \text{shear rate}$$

$$v = \dot{\gamma} y e_x \quad \rightarrow \text{velocity field}$$

$$\mu(\dot{\gamma}) = \frac{\tau(\dot{\gamma})}{\dot{\gamma}}, \quad \mu(\dot{\gamma}) > 0$$

shear-viscosity function  
(apparent viscosity)

at constant shear rate:

- **Thixotropic fluids** (apparent viscosity decreasing in time)
- **Rheopectic fluids** (apparent viscosity increasing in time)



# SHEAR-THINNING BLOOD FLOW MODELS

$$\mu_0 = \lim_{\dot{\gamma} \rightarrow 0} \mu(\dot{\gamma}) = 0.056 \text{Pas}$$

$$\mu_\infty = \lim_{\dot{\gamma} \rightarrow \infty} \mu(\dot{\gamma}) = 0.00345 \text{Pas}$$

MODEL	$\frac{\mu(\dot{\gamma}) - \mu_\infty}{\mu_0 - \mu_\infty}$	MATERIAL CONSTANTS FOR BLOOD
POWELL-EYRING	$\frac{\sinh^{-1}(\lambda\dot{\gamma})}{\lambda\dot{\gamma}}$	$\lambda = 5.383s$
CROSS	$(1 + (\lambda\dot{\gamma})^m)^{-1}$	$\lambda = 1.007s, m = 1.028$
MODIFIED CROSS	$(1 + (\lambda\dot{\gamma})^m)^{-a}$	$\lambda = 3.736s, m = 2.406, a = 0.254$
CARREAU	$(1 + (\lambda\dot{\gamma})^2)^{(n-1)/2}$	$\lambda = 3.313s, n = 0.3568$
CARREAU-YASUDA	$(1 + (\lambda\dot{\gamma})^a)^{(n-1)/a}$	$\lambda = 1.902s, n = 0.22, a = 1.25$

(Y.I.Cho and K.R.Kensey, *Biorheology*, 1991)

# BLOOD RHEOLOGY

- Anne M. Robertson, Adélia Sequeira and Marina V. Kameneva. **Hemorheology**. In: *Hemodynamical Flows: Modeling, Analysis and Simulation*, G. P. Galdi, R. Rannacher, A. M. Robertson, S. Turek, Oberwolfach Seminars, Vol. 37, pp.63-120, 2008.
- Anne M. Robertson, Adélia Sequeira and Robert Owens. **Rheological models for blood**. In: *Cardiovascular Mathematics*, A. Quarteroni, L. Formaggia and A. Veneziani (eds.), Springer-Verlag, 2009.

# BLOOD FLOW DYNAMICS

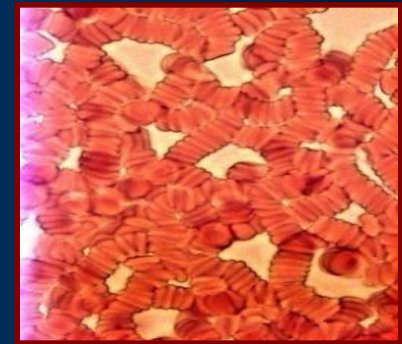
## Blood flow: Generalized Newtonian fluid equations

$$\rho \left( \frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) + \nabla p - \nabla \cdot \boldsymbol{\tau}(\mathbf{u}) = 0 \quad \text{in } \Omega$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{in } \Omega$$

$$\boldsymbol{\tau}(\mathbf{u}) = 2\mu(\dot{\gamma})\mathbf{D}(\mathbf{u}) \quad \text{in } \Omega$$

$$\mathbf{D}(\mathbf{u}) = \frac{1}{2}(\nabla \mathbf{u} + (\nabla \mathbf{u})^T), \quad \dot{\gamma} = \sqrt{2\mathbf{D}(\mathbf{u}) : \mathbf{D}(\mathbf{u})}$$



Rouleaux aggregation

## Shear-thinning viscosity Carreau model

$$\frac{\mu(\dot{\gamma}) - \mu_{\infty}}{\mu_0 - \mu_{\infty}} = [1 + (\lambda\dot{\gamma})^2]^{(n-1)/2}, \quad n \leq 1 \quad \rightarrow$$

$$\mu_0 = \lim_{\dot{\gamma} \rightarrow 0} \mu(\dot{\gamma}) = 0.056 Pa \cdot s$$

$$\mu_{\infty} = \lim_{\dot{\gamma} \rightarrow \infty} \mu(\dot{\gamma}) = 0.00345 Pa \cdot s$$

$$\lambda = 3.313 s$$

$$n = 0.3568$$

# MATHEMATICAL RESULTS

If the correspondence  $\mathbf{T} \rightarrow \mu(|\mathbf{T}|^2)\mathbf{T}$  satisfies, for some  $p > 1$ , and for every symmetric second order tensors  $\mathbf{A}, \mathbf{B}$ , the relations

$$\begin{aligned} \mu(|\mathbf{A}|^2)\mathbf{A} &: \mathbf{A} \geq C|\mathbf{A}|^p \\ |\mu(|\mathbf{A}|^2)\mathbf{A}| &\leq C(1 + |\mathbf{A}|)^{p-1} \\ (\mu(|\mathbf{A}|^2)\mathbf{A} - \mu(|\mathbf{B}|^2)\mathbf{B}) &: (\mathbf{A} - \mathbf{B}) > 0 \end{aligned}$$

then for  $f \in L^{p'}(\Omega)$  and  $p > \frac{2d}{d+1}$ , there exists a weak solution  $\mathbf{u} \in W^{1,p}(\Omega)$ ,

$$\int_{\Omega} \mu(\dot{\gamma}) \mathbf{D}\mathbf{u} : \mathbf{D}\mathbf{v} + \int_{\Omega} (\mathbf{u} \cdot \nabla \mathbf{u}) \cdot \mathbf{v} = \int_{\Omega} \mathbf{f} \cdot \mathbf{v}, \quad \forall \mathbf{v} \in \mathcal{V}.$$

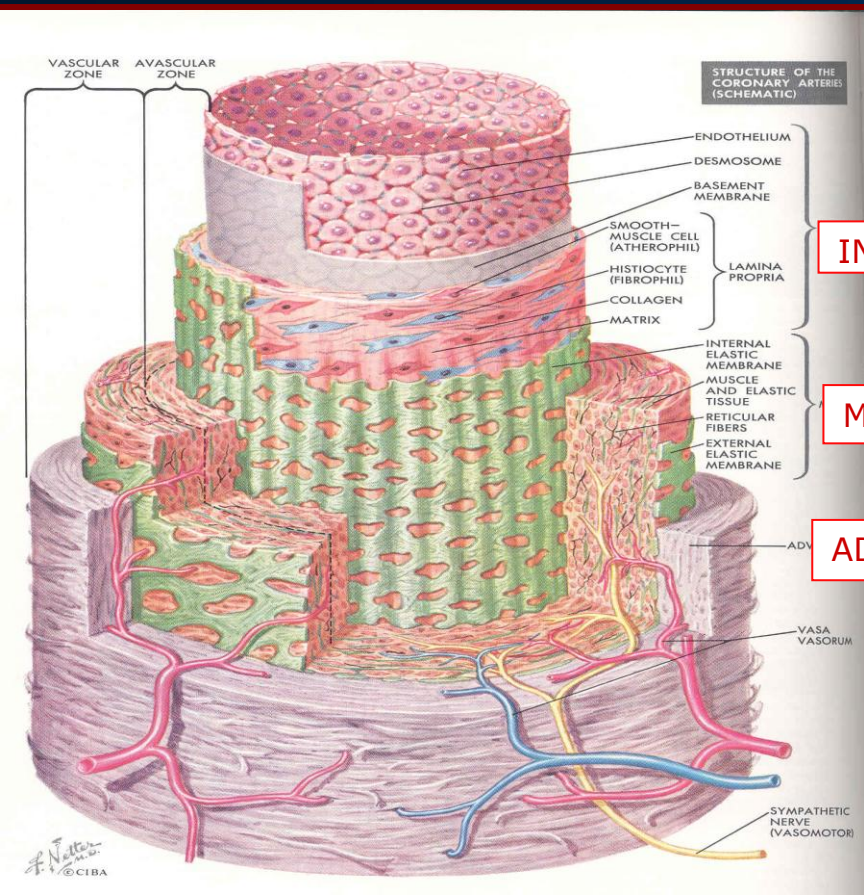
$$p > \frac{3d+2}{d+2} \quad (\text{unsteady, Ladyzhenskaya (1968-70), Lions(1969)})$$

$$p > \frac{3d}{d+2} \quad (\text{unsteady, space periodic, Bellout(1994), Málek(1996)})$$

$$p \geq \frac{3d}{d+2} \quad (\text{steady, Lions(1969)})$$

$$p > \frac{2d}{d+1} \quad (\text{steady, Frehse(1997), Ruzicka(1997), Arada and Sequeira(2005)})$$

# MORPHOLOGY OF THE BLOOD VESSELS



**Mechanical model of the arterial vessel:** linear or non-linear elasticity in Lagrangian formulation

↓

**Mechanical interaction**  
(Fluid-wall coupling)

The vessel wall is formed by many layers made of tissues with different mechanical characteristics

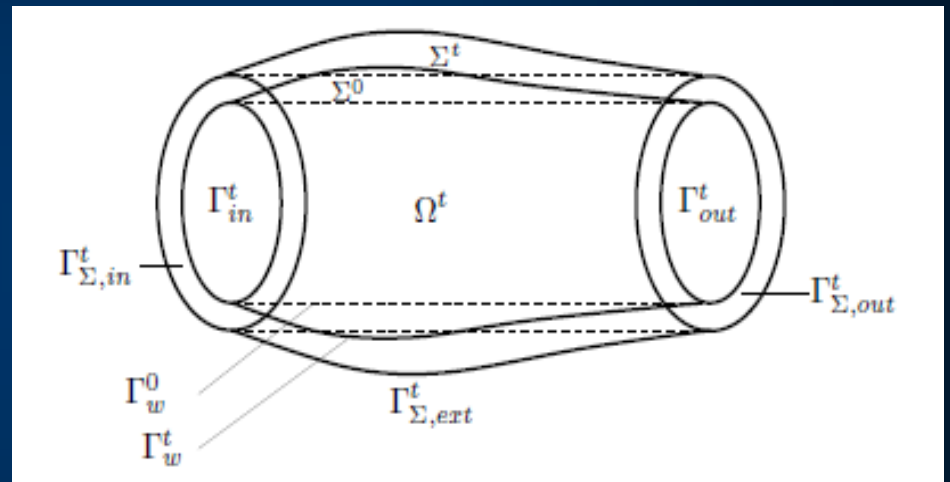
# MECHANICAL FLUID-STRUCTURE INTERACTION

## Equations for the deformation of the vessel wall

3D nonlinear hyperelasticity (Lagrangian formulation)

$\Sigma^t \subset \mathbb{R}^3 \longrightarrow$  structure domain

$\Sigma^0 \longrightarrow$  reference configuration



$$\partial \Sigma^t = \Gamma_{\omega}^t \cup \Gamma_{\Sigma,ext}^t \cup \Gamma_{\Sigma,in}^t \cup \Gamma_{\Sigma,out}^t$$

$$\partial \Sigma^0 = \Gamma_{\omega}^0 \cup \Gamma_{\Sigma,ext}^0 \cup \Gamma_{\Sigma,in}^0 \cup \Gamma_{\Sigma,out}^0 \longrightarrow \text{reference boundaries}$$

# MECHANICAL FLUID-STRUCTURE INTERACTION

## 3D nonlinear hyperelasticity (Lagrangian formulation)

$$\rho_w \frac{\partial^2 \eta}{\partial t^2} - \nabla_0 \cdot \sigma(\eta) = 0 \quad \text{in } \Sigma^0, \forall t \in I$$

$\eta$   $\Rightarrow$  displacement vector

$\rho_w$   $\Rightarrow$  wall density

$\sigma(\eta) = F(\eta)S(\eta) = (I + \nabla_0 \eta)S(\eta)$   $\Rightarrow$  first Piola-Kirchhoff tensor

deformation  
gradient tensor

second Piola-Kirchhoff  
tensor



# MECHANICAL FLUID-STRUCTURE INTERACTION

## 3D nonlinear hyperelasticity (Lagrangian formulation)

Green-St Venant strain tensor

$$E = E(\eta) = \frac{1}{2}(F^T F - I) = \frac{1}{2}\left((\nabla_0 \eta)^T + \nabla_0 \eta + (\nabla_0 \eta)^T \nabla_0 \eta\right)$$

St Venant – Kirchhoff material

$$S(\eta) = \lambda \operatorname{tr}(E) I + 2\nu E \quad (\text{linear response})$$

with

$\lambda(\bar{E}, \xi), \nu(\bar{E}, \xi) \longrightarrow$  Lamé constants (functions of Young modulus, Poisson ratio)

# MECHANICAL FLUID-STRUCTURE INTERACTION

Equations for the deformation of the vessel wall (Lagrangian formulation)

$$\rho_w \frac{\partial^2 \eta}{\partial t^2} - \nabla_0 \cdot \sigma(\eta) = 0 \quad \text{in } \Sigma^0$$

$$\eta = \eta_0 \quad \text{for } t = 0, \quad \text{in } \Sigma^0$$

$$\frac{\partial \eta}{\partial t} = \frac{\partial \eta_0}{\partial t} \quad \text{for } t = 0, \quad \text{in } \Sigma^0$$

$$\sigma(\eta) \cdot n_0 = \hat{\phi} \quad \text{on } \Gamma_{\omega}^0$$

$$\sigma(\eta) \cdot n_0 = 0 \quad \text{on } \Gamma_{\Sigma, ext}^0$$

$$\eta = 0 \quad \text{on } \Gamma_{\Sigma, out}^0$$

$$\eta = 0 \quad \text{on } \Gamma_{\Sigma, in}^0$$

+ compatibility conditions

$$\frac{\partial \eta_0}{\partial t} = u_0 \quad \text{on } \Gamma_{\omega}^0$$

&

interface conditions

(clamped structure) 

initial

&

boundary  
conditions

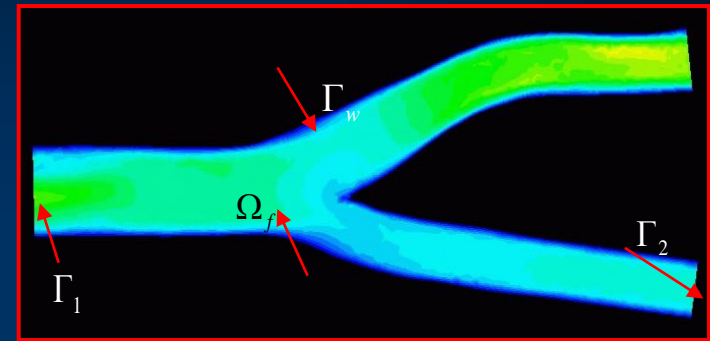
# MECHANICAL FLUID-STRUCTURE INTERACTION

- ◆ **Blood flow:** Generalized Newtonian flow (ALE frame)

$$\rho \left( \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} - \mathbf{w}) \cdot \nabla \mathbf{u} \right) + \nabla p - \nabla \cdot \boldsymbol{\tau}(\mathbf{u}) = 0 \quad \text{in } \Omega_f$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{in } \Omega_f$$

$$\boldsymbol{\tau}(\mathbf{u}) = 2\mu(\dot{\gamma})\mathbf{D}(\mathbf{u}) \quad \text{in } \Omega_f$$



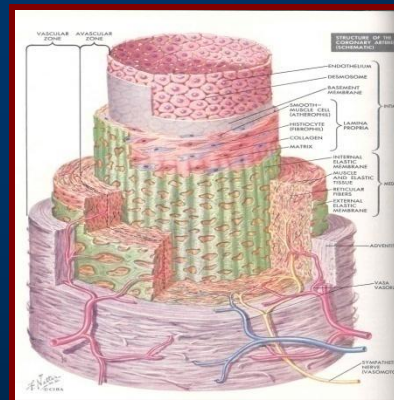
- ◆ **Deformation of the vessel wall**

$$\rho_w \frac{\partial^2 \eta}{\partial t^2} - \nabla_0 \cdot \boldsymbol{\sigma}(\eta) = 0 \quad \text{in } \Sigma^0$$

- ◆ **Interface conditions**

$$\boldsymbol{\sigma}(\eta) \cdot \mathbf{n} = -p\mathbf{n} + \boldsymbol{\tau}(\mathbf{u}) \cdot \mathbf{n} \quad \text{at } \Gamma_w$$

$$\mathbf{u} = \frac{\partial \eta}{\partial t} \quad \text{at } \Gamma_w$$



$u$  = blood velocity  
 $w$  = domain velocity  
 $p$  = pressure  
 $\rho_f$  = density  
 $\mu$  = viscosity  
 $\eta$  = wall displacement

+ initial and boundary conditions at  $\Gamma_i$  ( $i=0,1,2$ )

# MECHANICAL FLUID-STRUCTURE INTERACTION

## ◆ Interface conditions

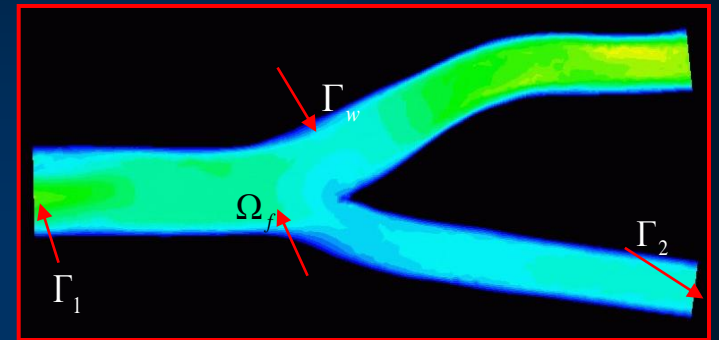
$$u = \frac{\partial \eta}{\partial t}, \quad \forall t \in I, \quad \text{at } \Gamma_\omega^t$$

$$\sigma(\eta) \cdot n = -pn + \tau(u) \cdot n, \quad \forall t \in I, \quad \text{at } \Gamma_\omega^t$$



(using the Piola transform)

$$-(\det \nabla_0 \eta) \tau(u, p) (\nabla_0^{-T} \eta) \cdot n_0 = \sigma(\eta) \cdot n_0, \quad \forall t \in I, \quad \text{on } \Gamma_\omega^t$$



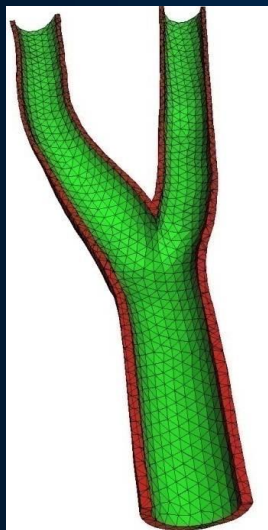
# MECHANICAL FLUID-STRUCTURE INTERACTION

## Blood:

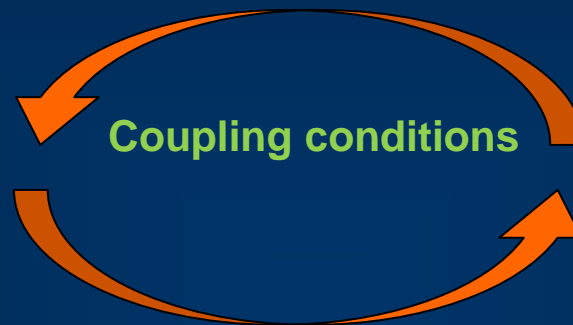
Newtonian or non-Newtonian fluid

## Deformation of the Vessel Wall:

3D (nonlinear) elasticity or 2D shell type models

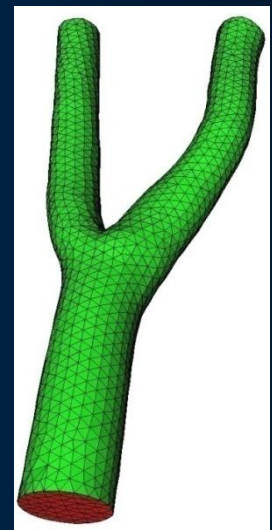


Displacement (new domain)



Normal stress

implicit coupling  
(iterative procedure)



## Open problems:

### Well posedness of the FSI problem

Contributions given by e.g. : D.Coutand, S. Shkoller, Y.Maday, C.Grandmont, B.Desjardins, M.Esteban, G.P. Galdi, H.Beirão da Veiga, among others

### Devise efficient numerical algorithms

Contributions given by e.g. : P. le Tallec, F.Nobile, M.A.Fernandéz, M.Moubachir, J-F.Gerbeau, S.Deparis, W.A.Wall, among others

# MECHANICAL FLUID-STRUCTURE INTERACTION

## Regularity Assumptions:

$\Omega^t \subset \mathbb{R}^3$  is open and connected

$\partial\Omega^t = \Gamma_{\omega}^t \cup \Gamma_{in}^t \cup \Gamma_{out}^t$  Is locally Lipschitz ( $\partial\Omega^t \in C^{1,1}$ )

$$\frac{\partial \eta}{\partial t} \in H^{1/2}(\Gamma_{\omega}^t) \implies u(t) \in H^1(\Omega^t), \forall t$$

# MECHANICAL FLUID-STRUCTURE INTERACTION

## An Energy Estimate for the coupled FSI problem

[ J. Janela, A. Moura, A. S, 2009 – generalization of L. Formaggia, A. Moura, F. Nobile, 2007 ]

$$E(t) = \frac{\rho}{2} \|u\|_{L^2(\Omega^t)}^2 + \frac{\rho_w}{2} \left\| \frac{\partial \eta}{\partial t} \right\|_{L^2(\Sigma^0)}^2 + \mu(\gamma) \|E(\eta)\|_{L^2(\Sigma^0)}^2 + \frac{\lambda}{2} \|\text{tr}E(\eta)\|_{L^2(\Sigma^0)}^2$$

**THEOREM:** The coupled FSI problem, with homogeneous Dirichlet boundary conditions  $u = 0$  at  $\Gamma_{in}^t$  and  $\Gamma_{out}^t$  satisfies the following energy inequality

$$\frac{d}{dt} (E(t)) + 2\mu_\infty \|D(u)\|_{L^2(\Omega^t)}^2 \leq 0 \quad \text{and, consequently, the energy decay property}$$

$$E(t) + 2\mu_\infty \int_0^t \|D(u)\|_{L^2(\Omega^t)}^2 dt \leq E(0) \quad \text{where } E(0) \text{ is a constant depending only on the initial data } u_0, \eta_0, \eta_0$$

REMARK:  $\int_{\Gamma_{in}^t} |u|^2 u \cdot n > 0, \int_{\Gamma_{out}^t} |u|^2 u \cdot n > 0$  for homogeneous Neumann conditions



# MECHANICAL FLUID-STRUCTURE INTERACTION

## Sketch of the PROOF:

1. Multiply the structure equation by  $\frac{\partial \eta}{\partial t}$ , integrate over the reference domain, use the boundary and matching conditions
2. Multiply the fluid equation by  $u$ , integrate over the fluid domain, ...

3.  $\mu_\infty \leq \mu(\gamma) \leq \mu_0$  (shear-thinning viscosity fluid)

$$\Rightarrow \int_{\Omega^t} 2\mu(\gamma) D(u) : \nabla u \, d\omega \geq 2\mu_\infty \|D(u)\|_{L^2(\Omega^t)}^2$$

Finally 
$$\frac{d}{dt} (E(t)) + 2\mu_\infty \|D(u)\|_{L^2(\Omega^t)}^2 + \frac{\rho}{2} \int_{\Gamma_{in}^t \cup \Gamma_{out}^t} |u|^2 u \cdot n \, d\gamma \leq \int_{\Gamma_{in}^t \cup \Gamma_{out}^t} (\tau(u) \cdot n) \cdot u \, d\gamma$$

# MECHANICAL FLUID-STRUCTURE INTERACTION

**FSI Algorithm:** (adapted from Fernández & Moubachir, 2005)

ALE formulation to account for the evolution of the computational domain

Efficient solvers for each fluid and structure subproblems to ensure accurate and fast convergence of the FSI nonlinear coupled system

**Fluid equations:**

**Discretization in time:** implicit Euler scheme

**Discretization in space:** stabilized P1 bubble / P1 FE

**Structure equations:**

**Discretization in time:** mid-point Newmark method

**Discretization in space:** P1 FE

**Coupling strategy:** fully implicit coupling based on a Newton algorithm with the exact computation of the Jacobian

# BLOOD FLOW SIMULATIONS

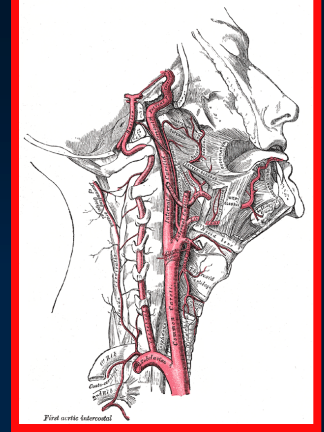
## Newtonian vs non-Newtonian behavior

### Main objectives:

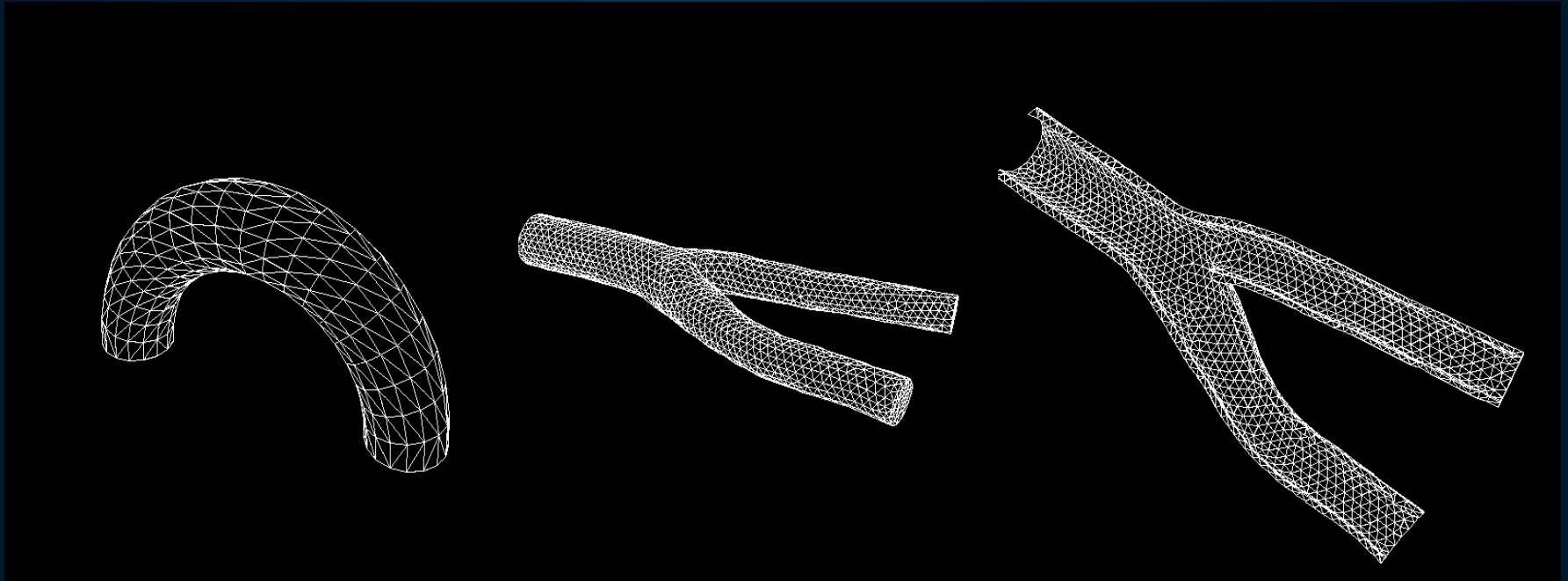
- 3D **Non-Newtonian models** for blood flow
- 3D **Fluid-Structure Interaction** algorithms for pressure wave propagation in arteries and detailed flow patterns using Newtonian and non-Newtonian blood flow models
- **Geometrical multiscale** simulation of the cardiovascular system using non-Newtonian models

# BLOOD FLOW SIMULATIONS

Idealized vs reconstructed geometries  
&  
computational grids



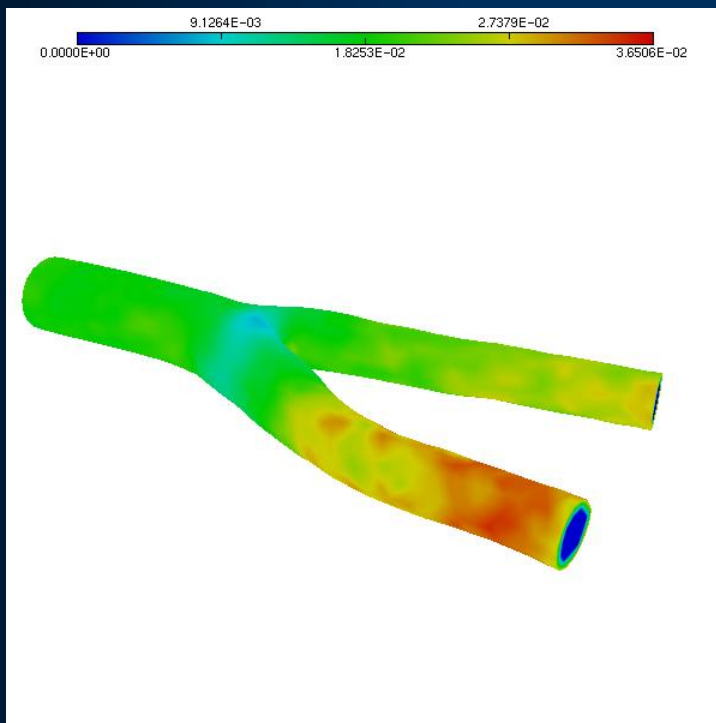
carotid  
bifurcation



# BLOOD FLOW SIMULATIONS

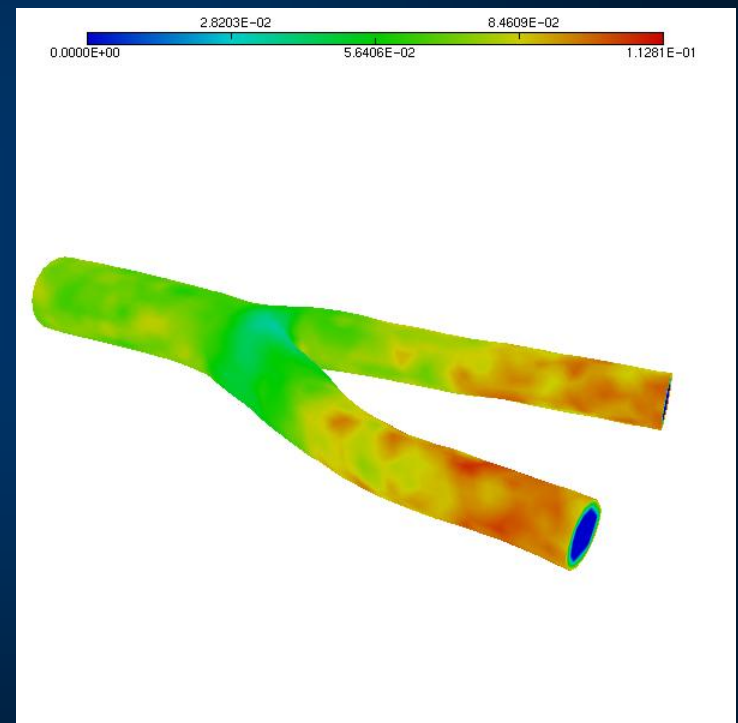
## Newtonian vs non-Newtonian

### Carotid Bifurcation: Wall Shear Stress (WSS)



Carreau model

A. Moura & J. Janela



Newtonian model  
 $\mu_{\infty} = 0.0035 \text{ Pas}$

# BLOOD FLOW SIMULATIONS

## Carreau model

### Curved vessel: Pressure

#### Fluid:

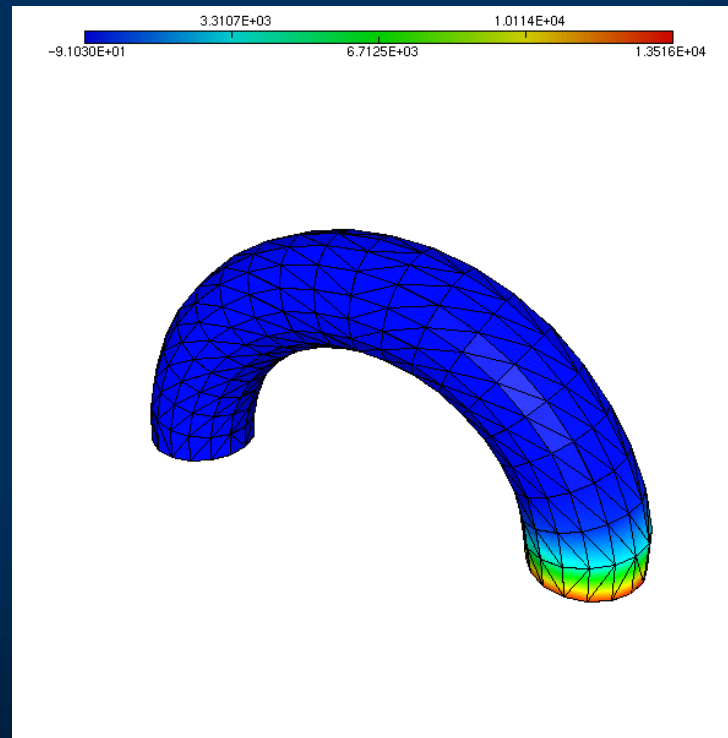
$$\mu_0 = \lim_{\gamma \rightarrow 0} \mu(\gamma) = 0.056 \text{ Pas}$$

$$\mu_\infty = \lim_{\gamma \rightarrow \infty} \mu(\gamma) = 0.00345 \text{ Pas}$$

$$\lambda = 3.313 \text{ s}$$

$$n = 0.3568$$

$$\rho = 1 \text{ g / cm}^3$$



#### Structure:

$$\lambda(E, \xi) = 3 \times 10^6 \text{ dynes / cm}^2$$

$$\nu(E, \xi) = 0.3$$

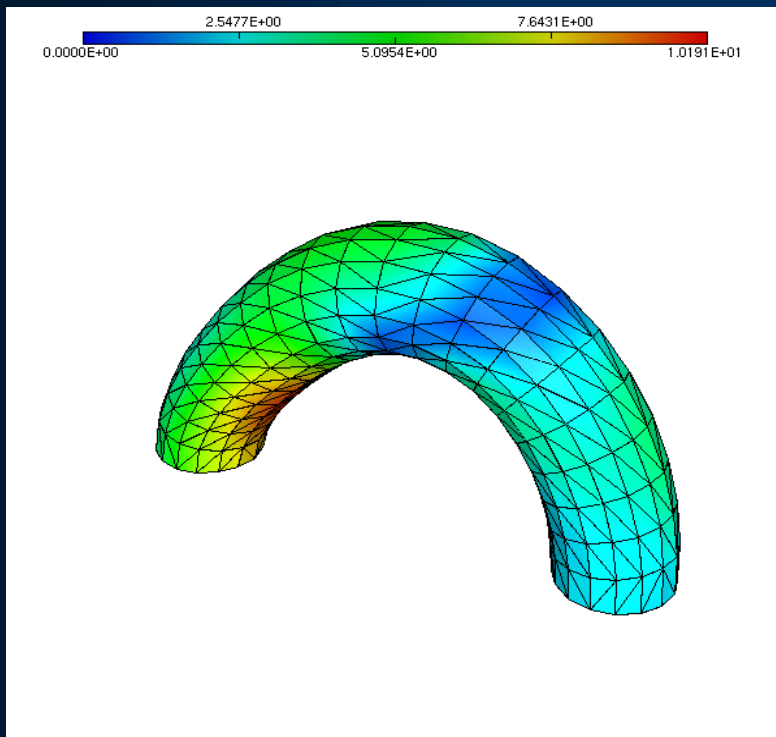
$$\rho_\omega = 1.2 \text{ g / cm}^3$$

$$h = 0.1 \text{ cm}$$

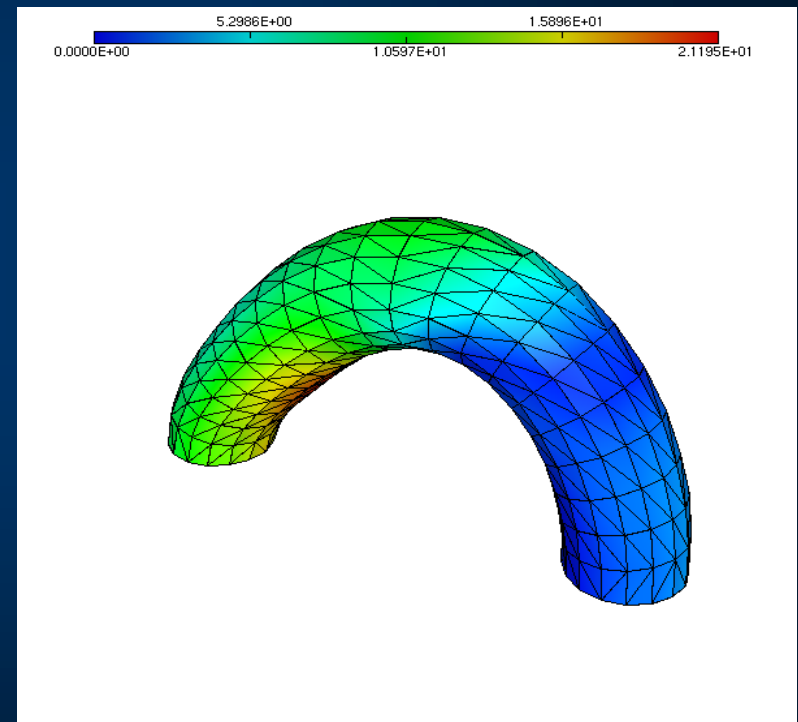
A. Moura & J. Janela

# BLOOD FLOW SIMULATIONS

## Newtonian vs non-Newtonian Curved vessel: Wall Shear Stress (WSS)



Carreau model



Newtonian model

$$\mu_{\infty} = 0.0035 \text{ Pas}$$

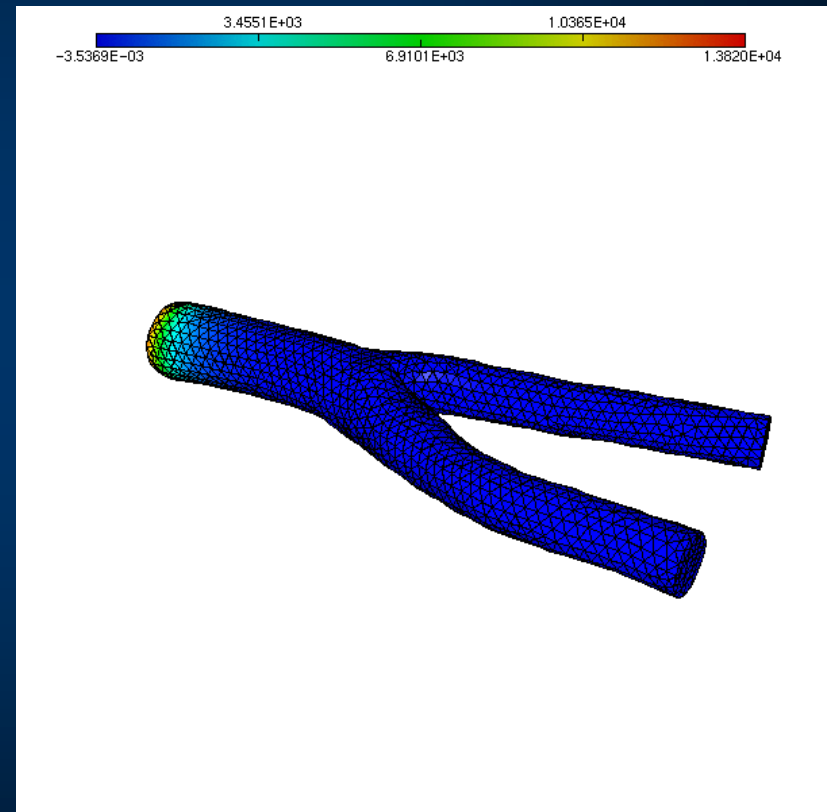
A. Moura & J. Janela



# BLOOD FLOW SIMULATIONS

## Carotid Bifurcation: Pressure pulse

Carreau model

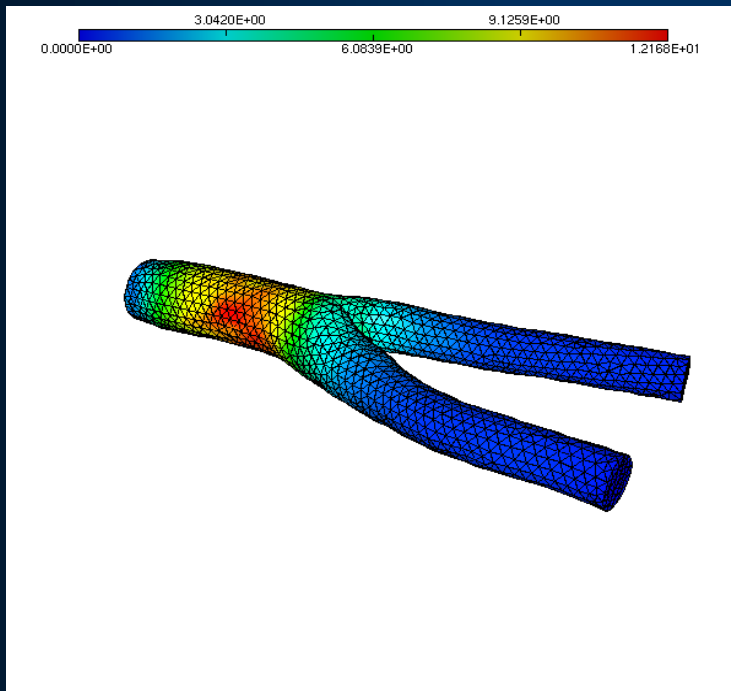


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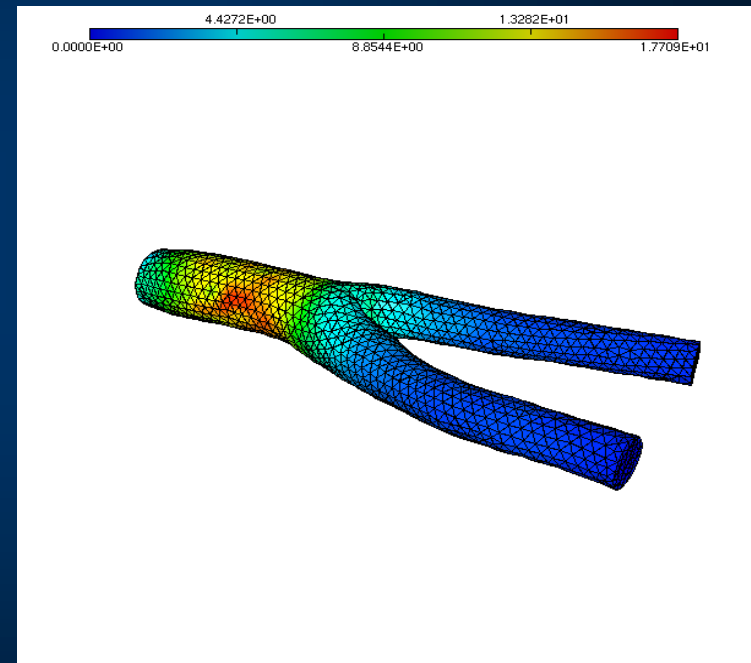
# BLOOD FLOW SIMULATIONS

## Newtonian vs non-Newtonian

### Carotid Bifurcation: Wall Shear Stress (WSS)



Carreau model

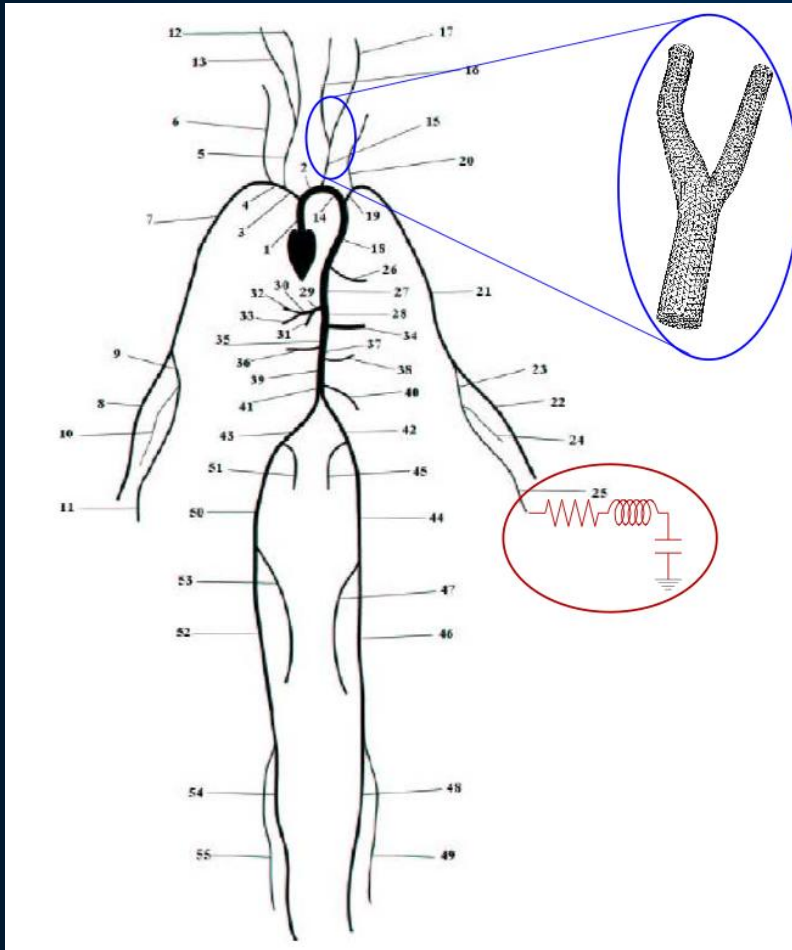


Newtonian model

$$\mu_{\infty} = 0.0035 \text{ Pas}$$

A. Moura & J. Janela

# GEOMETRICAL MULTISCALE

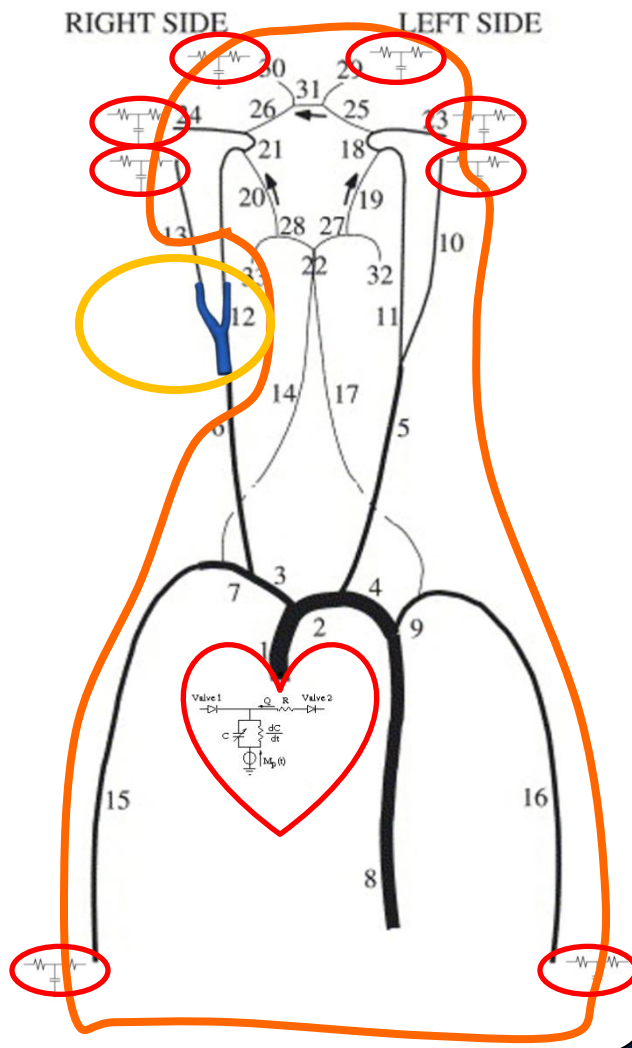


- Global features have influence on the local fluid dynamics
- Local changes in geometry or material properties (e.g. due to surgery, aging, stenosis, ...) may induce pressure waves reflections  
→ global effects

## Modeling strategy

- use the expensive 3D model only in the region of interest
- couple with network models that include peripheral impedances to account for global effects

# GEOMETRICAL MULTISCALE



Allows to take into account the global circulation in localized simulations and set proper boundary conditions

## 3D

- Very detailed simulations
- Very complex
- Computationally very costly

## 1D

- Evolution of mean pressure and flux in arteries
- System of hyperbolic equations
- Low computational cost

## 0D

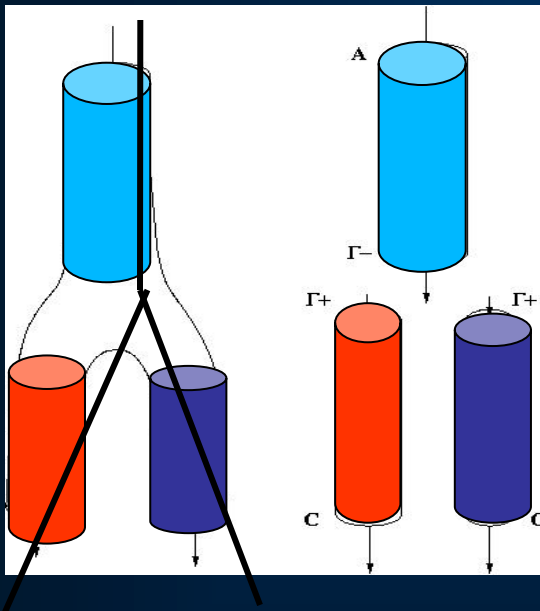
- Evolution in time of mean pressure and flux in wide compartments
- System of ODEs
- Very low computational cost

# GEOMETRICAL MULTISCALE

## 1D Model

Allows for the simulation of complex arterial networks!

### Domain decomposition



$$\left\{ \begin{array}{l} \frac{\partial A}{\partial t} + \frac{\partial Q}{\partial z} = 0 \\ \frac{\partial Q}{\partial t} + \alpha \frac{\partial}{\partial z} \left( \frac{Q^2}{A} \right) + \frac{A}{\rho} \frac{\partial P}{\partial z} + K \frac{Q}{A} = 0 \\ P - P_0 = \Psi(A) \end{array} \right.$$

Area  $\longrightarrow A(z, t) = \int_{\Omega \cap \Sigma(z)} d\gamma$

Flux  $\longrightarrow Q(z, t) = \int_{\Omega \cap \Sigma(z)} u_z(x, t) d\gamma$

Mean Pressure  $\longrightarrow P(z, t) = \frac{1}{|\Sigma(z)|} \int_{\Omega \cap \Sigma(z)} p(x, t) d\gamma$

- ▶ describes de wave propagation nature of blood flow
- ▶ acts as absorbing boundary condition for the 3D model
- ▶ simulation of complex arterial trees by coupling 1D models

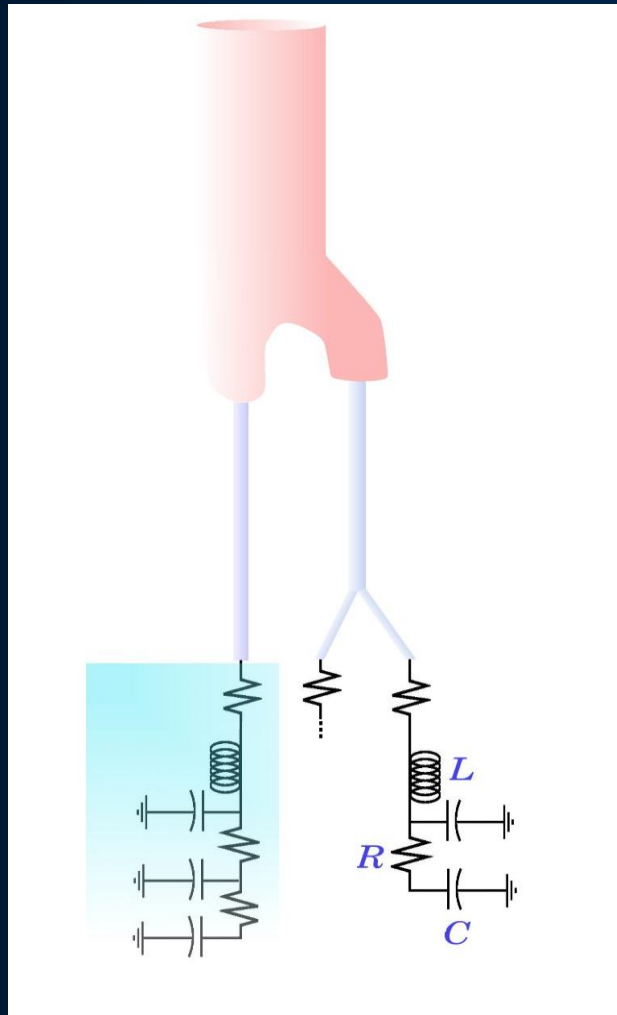
# GEOMETRICAL MULTISCALE

## 0D Model

0D Lumped parameters (system of linear ODE's)

$$C \frac{dP_i}{dt} = -(Q_{i+1} - Q_i),$$

$$L \frac{dQ_i}{dt} = -(P_i - P_{i-1}) - RQ_i$$



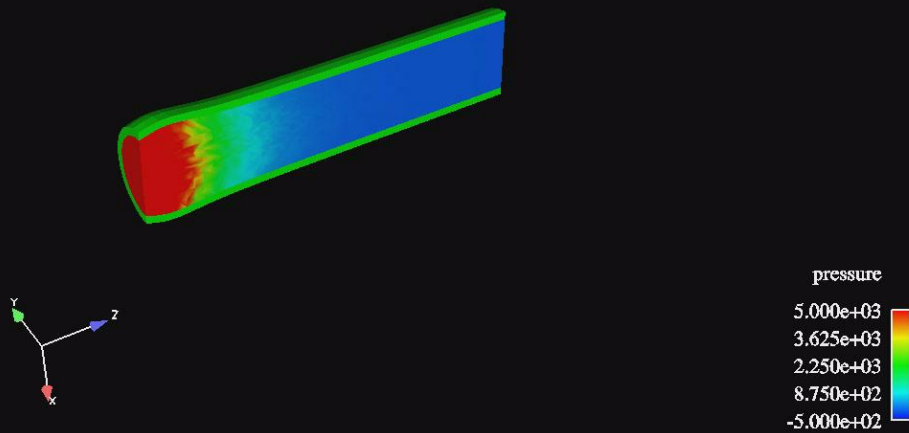
The analogy

Fluid dynamics	Electrical circuits
Pressure	Voltage
Flow rate	Current
Blood viscosity	Resistance R
Blood inertia	Inductance L
Wall compliance	Capacitance C

- RLC circuits model “large” arteries
- RC circuits account for capillary bed
- Can describe compartments (such as peripheral circulation)

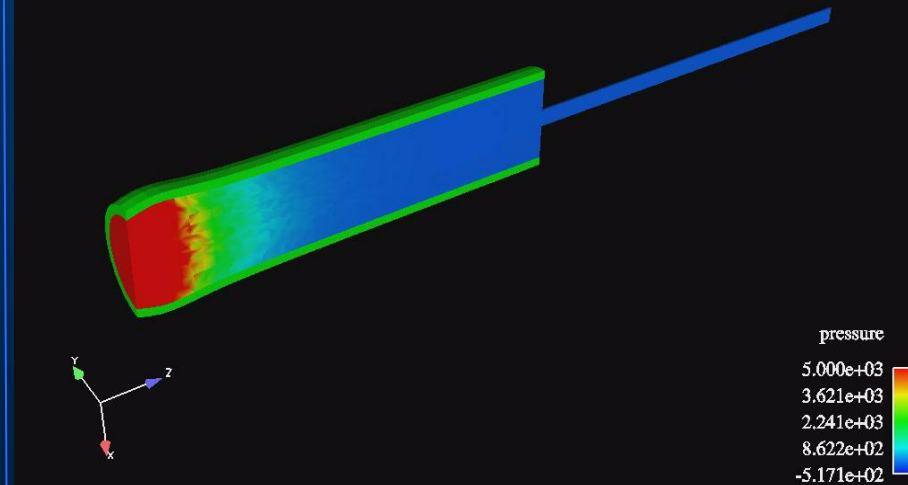
# GEOMETRICAL MULTISCALE

## 3D and 1D for a cylindrical artery: pressure pulse



(A. Moura)

3D model (spurious reflections)

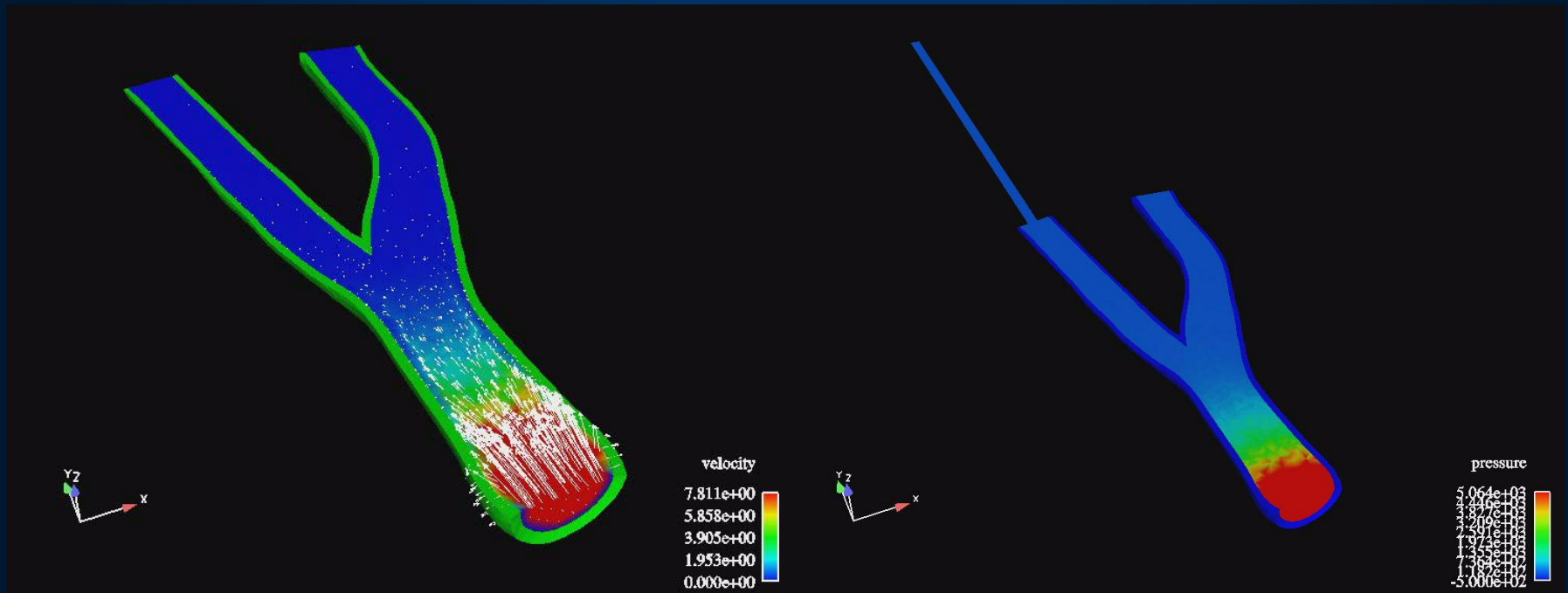


3D-1D coupled model



# GEOMETRICAL MULTISCALE

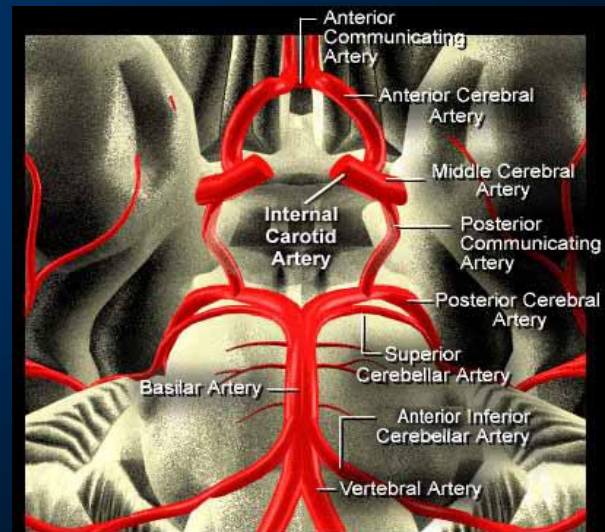
3D-1D for the carotid bifurcation: velocity field & pressure pulse



(A. Moura)

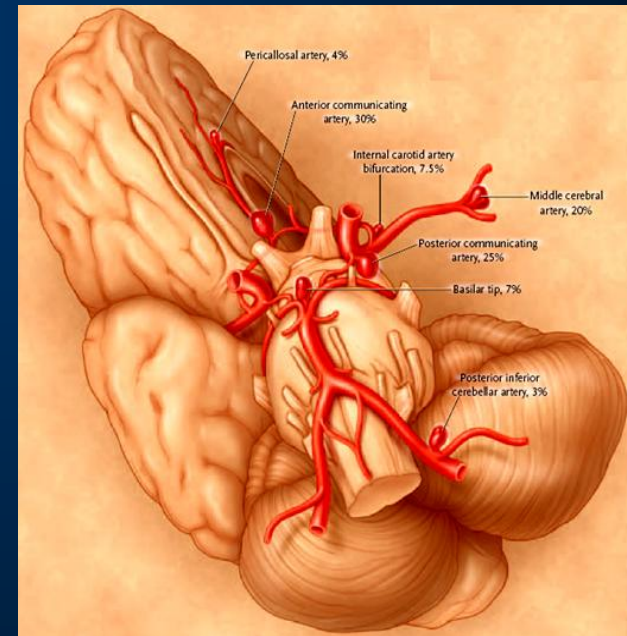
# MODELING CEREBRAL ANEURYSMS

- **Cerebral Aneurysms:**
  - Most common cause of hemorrhagic strokes
  - Tend to be silent until rupture
  - High prevalence, low risk
- **Main Goal:**
  - Help improve the evaluation & treatment of cerebral aneurysms
- **Our Approach:**
  - Patient-specific image-based CFD modeling to link hemodynamics & clinical observations



# MECHANISMS

- The mechanisms responsible for the development, growth and rupture of intracranial aneurysms are not well understood
- Better understanding of these processes can lead to better patient evaluation and improved treatments



# IMAGE-BASED MODELING OF BLOOD FLOWS



blood vessel  
imaging

$$\begin{aligned}\rho \left( \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} - \mathbf{w}) \cdot \nabla \mathbf{u} \right) + \nabla p - \nabla \cdot \boldsymbol{\tau}(\mathbf{u}) &= 0 \quad \text{in } \Omega_f \\ \nabla \cdot \mathbf{u} &= 0 \quad \text{in } \Omega_f \\ \boldsymbol{\tau}(\mathbf{u}) &= 2\mu(\dot{\gamma}) \mathbf{D}(\mathbf{u}) \quad \text{in } \Omega_f \\ \rho_w \frac{\partial^2 \eta}{\partial t^2} - \nabla_0 \cdot \boldsymbol{\sigma}(\eta) &= 0 \quad \text{in } \Sigma^0\end{aligned}$$

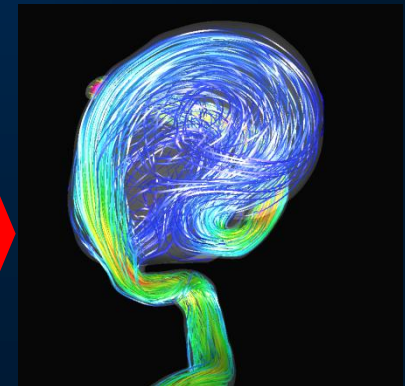
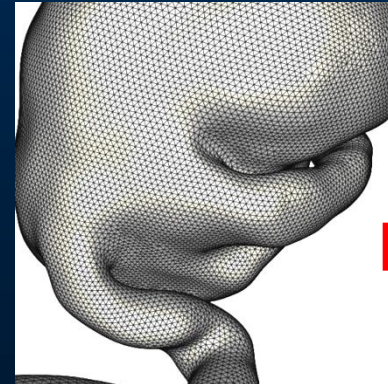
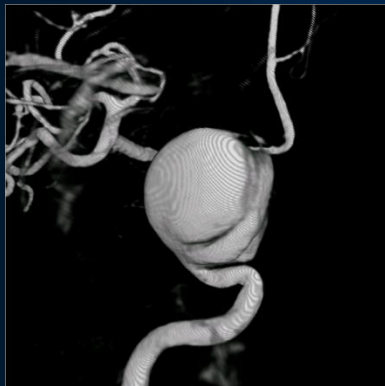


image  
processing

geometry  
modeling

meshing

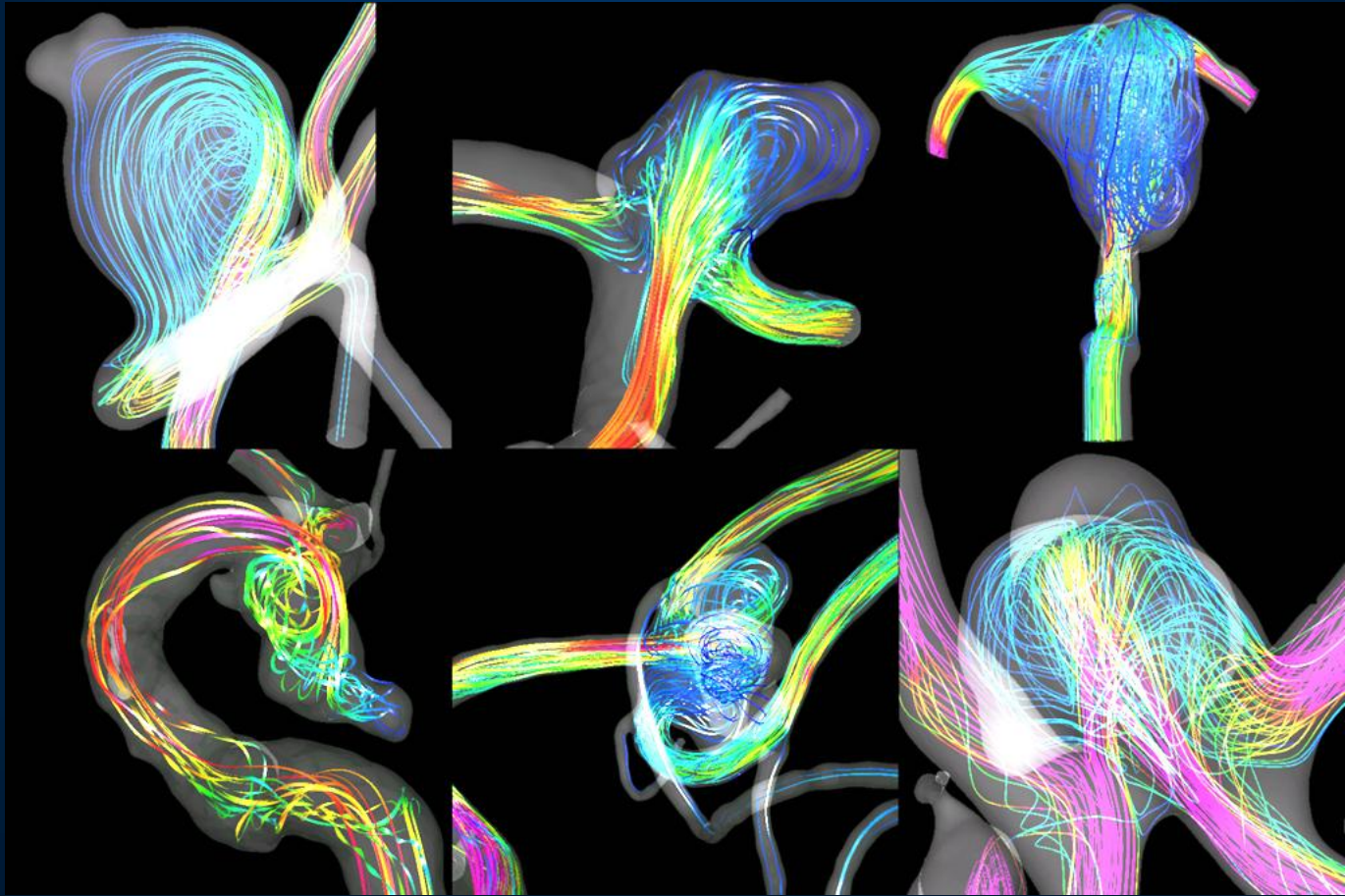
flow solution  
& visualization





# FLOW COMPLEXITY & STABILITY

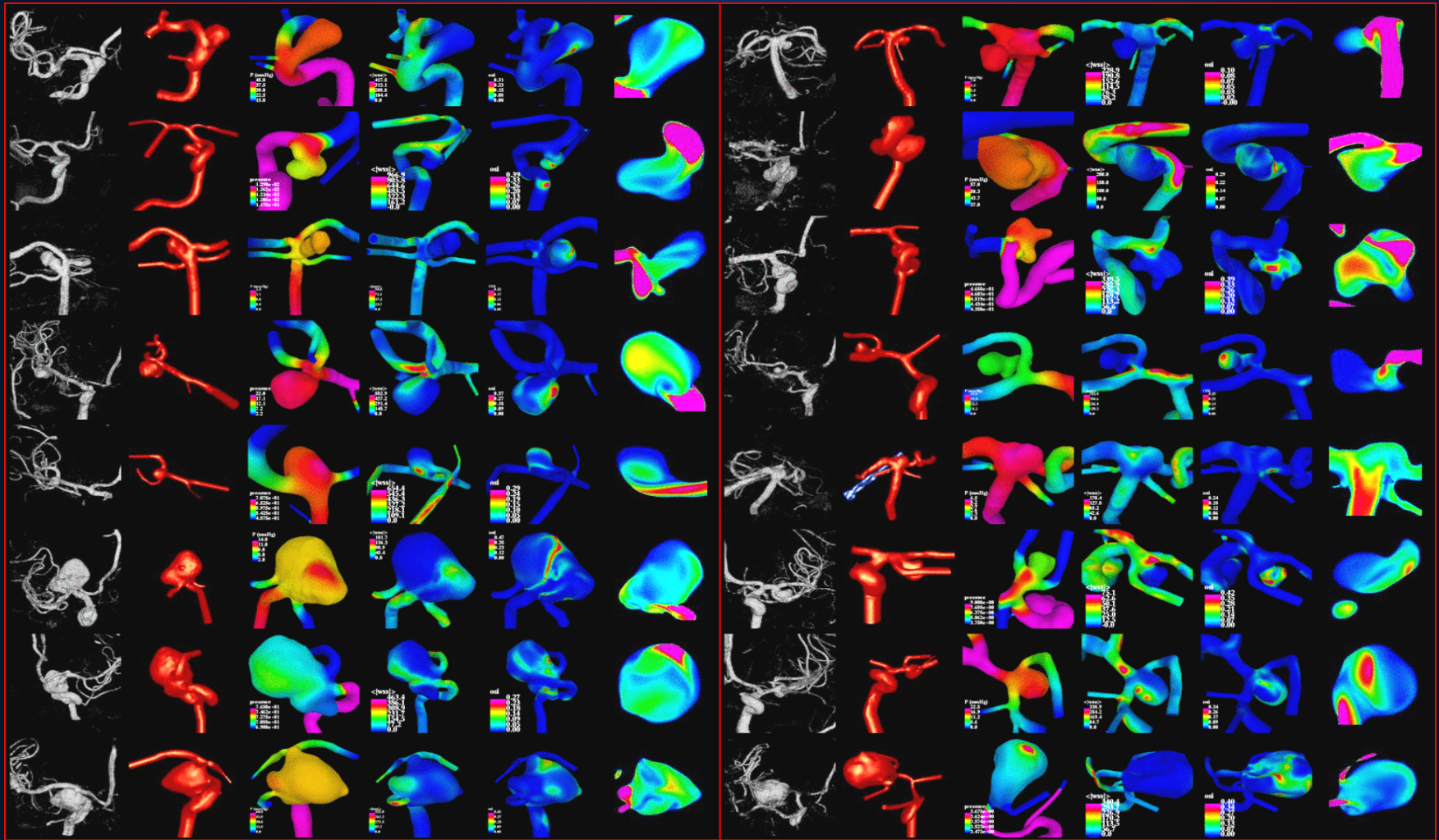
simple



J. Cebal, George Mason Univ

complex

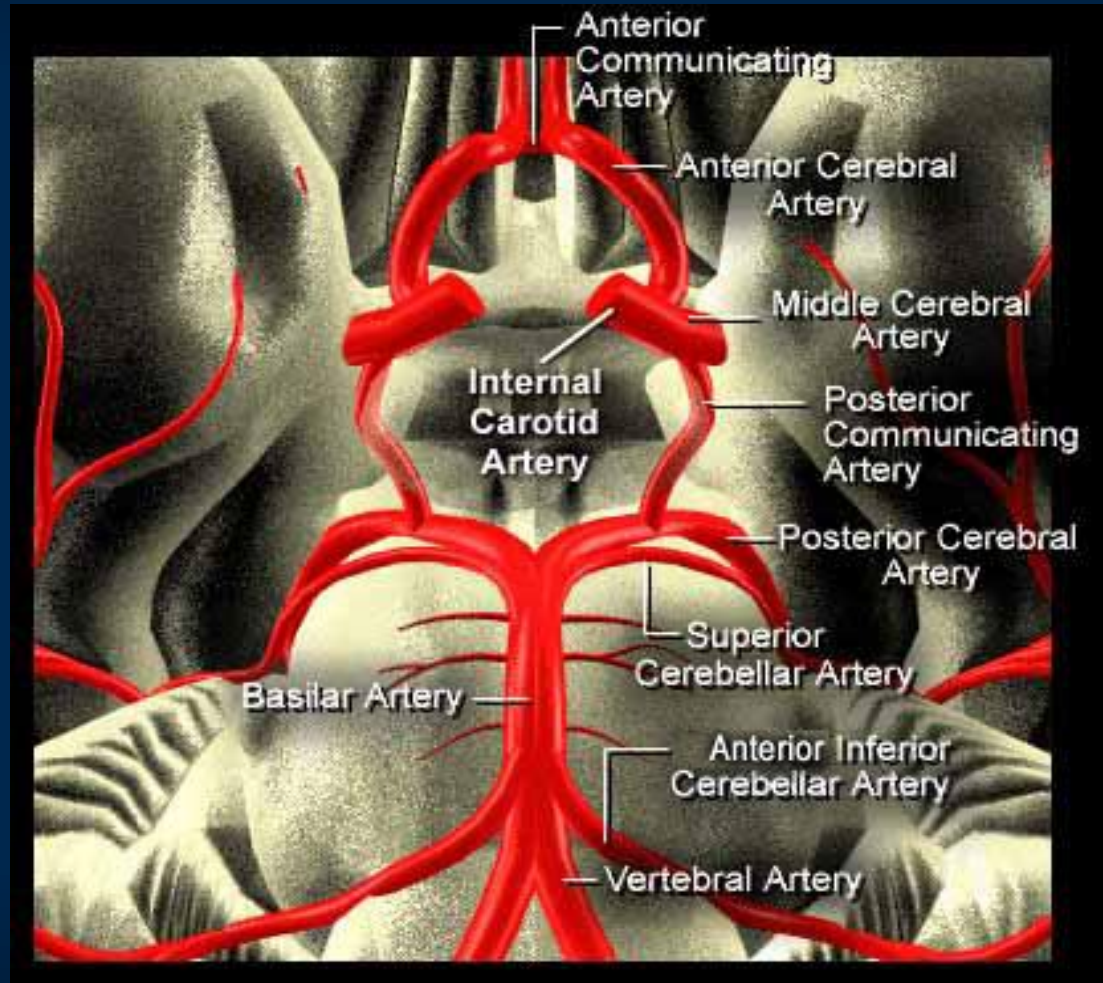
# DATABASE: ANEURYSM MODELS & CLINICAL INFO



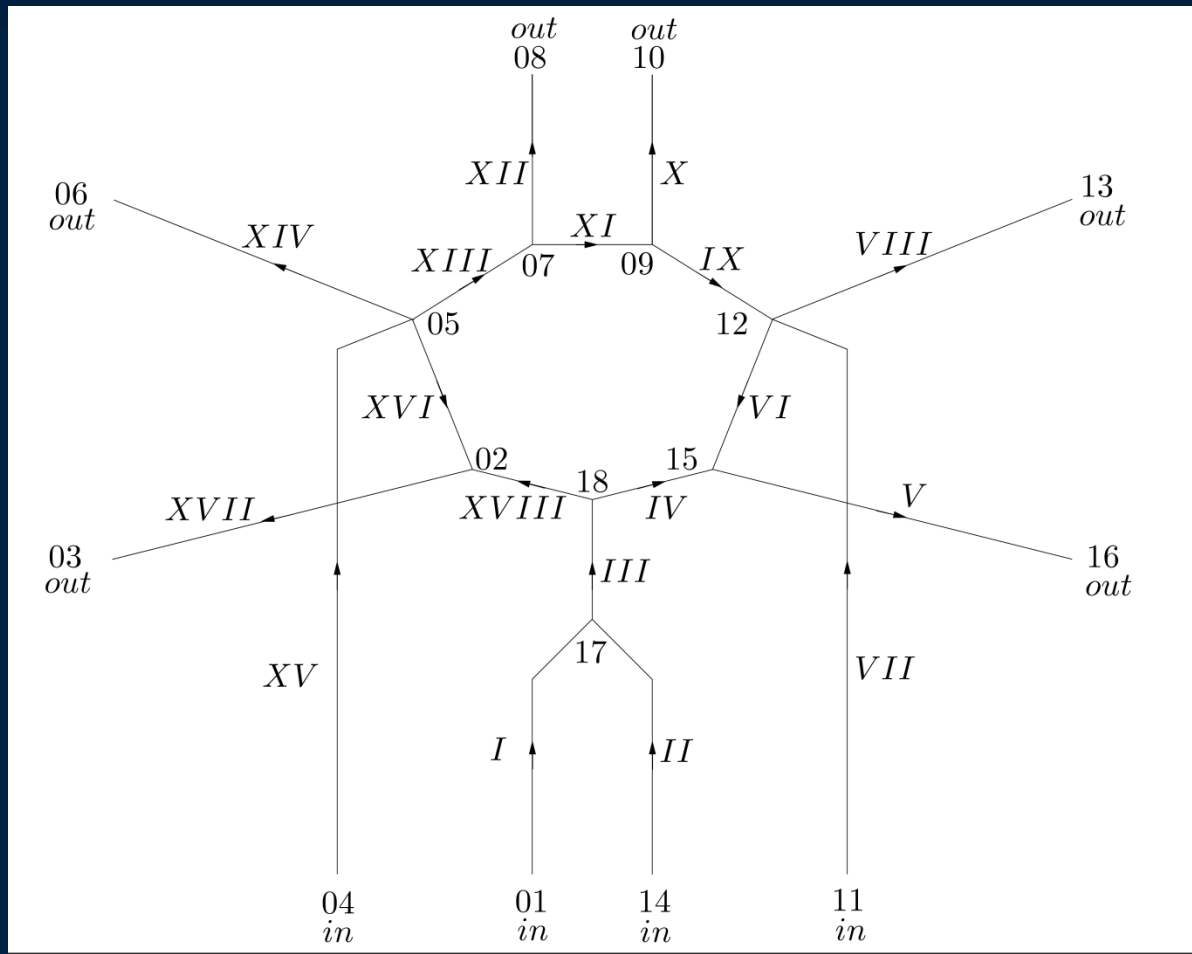
J. Cebral, George Mason Univ



## CIRCLE of WILLIS: 1D – NETWORK ?

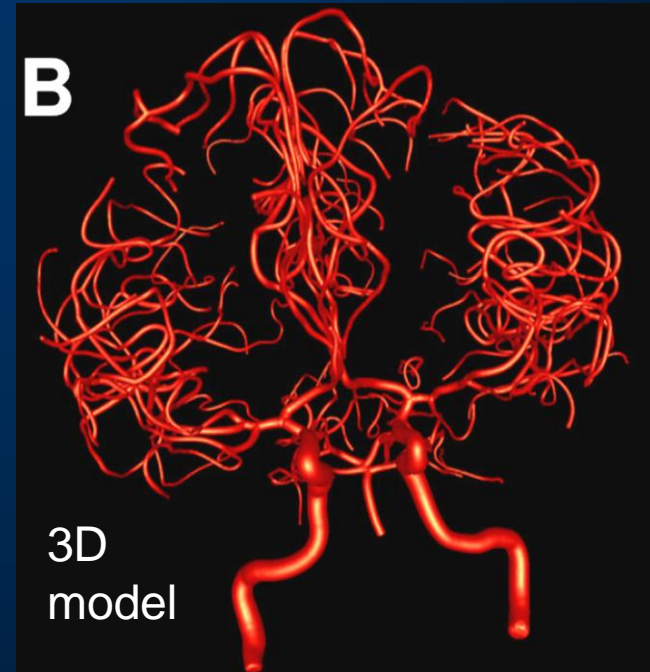
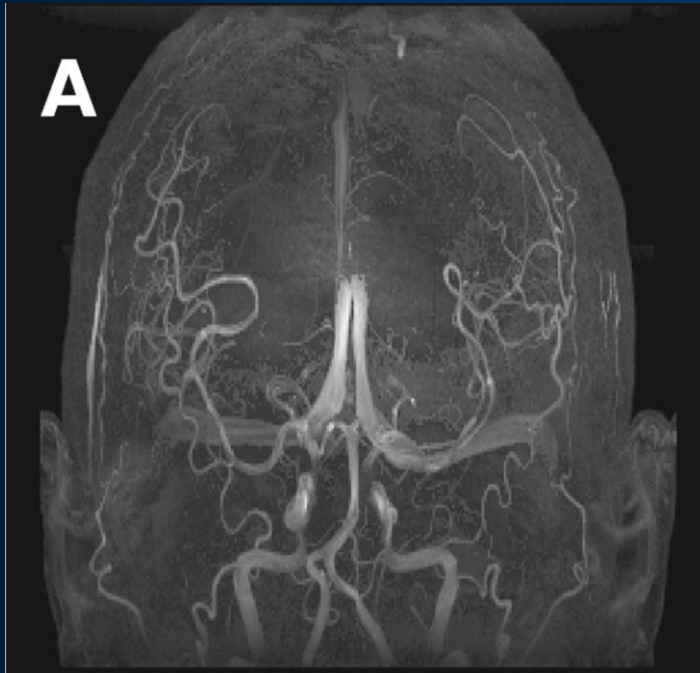


# CIRCLE of WILLIS: 1D - NETWORK





# MRA-BASED SUBJECT- SPECIFIC MODELING

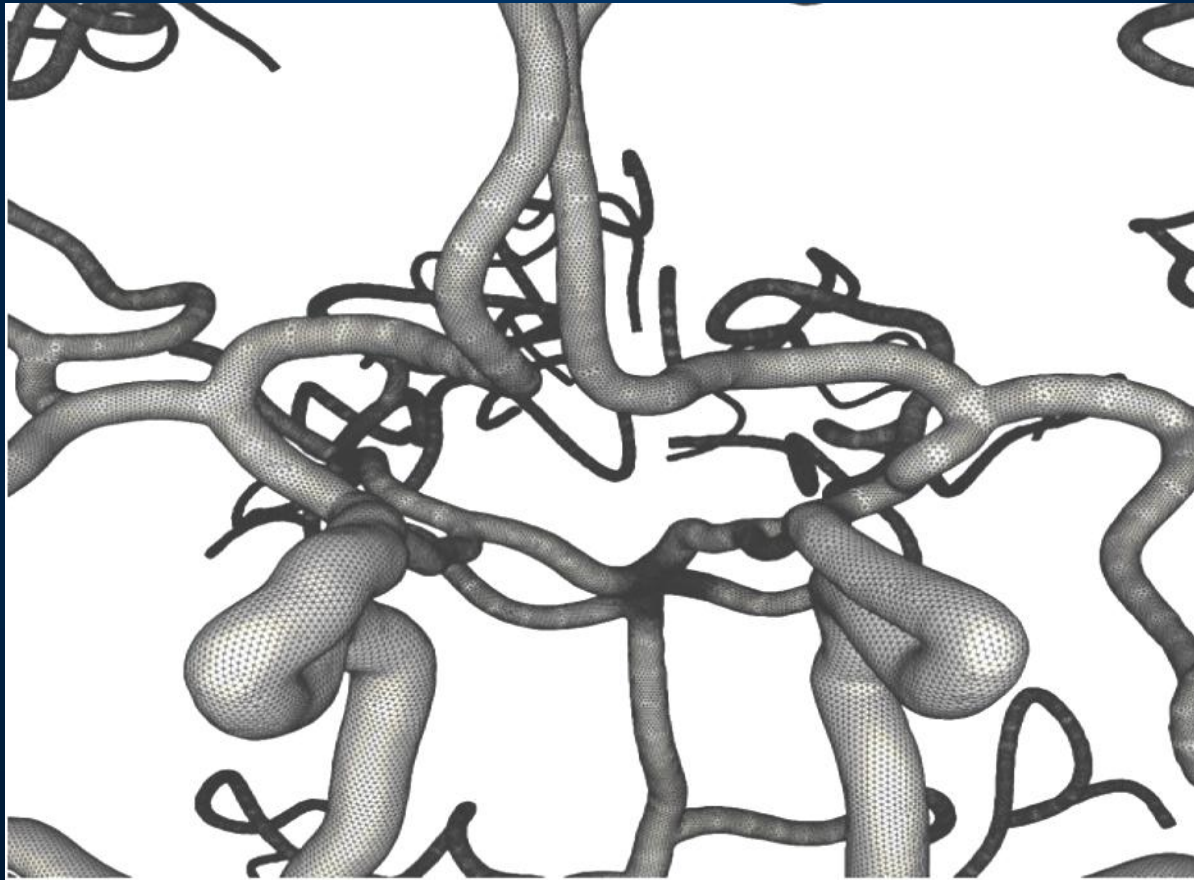


Semi-manual reconstruction  
Vector representation of  
arterial network



# FINITE ELEMENT MESH

Advancing front method  
>20 million tetrahedra



# CONCLUSIONS/ OUTCOME

Patient-specific CFD models are capable of realistically representing the *in vivo* hemodynamic characteristics

These models can be used to better understand the mechanisms of aneurysm growth and rupture

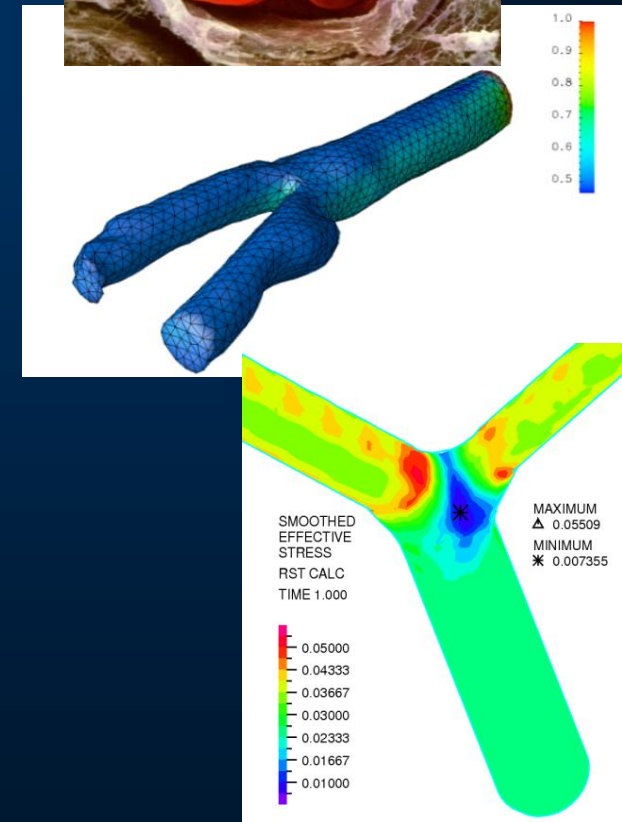
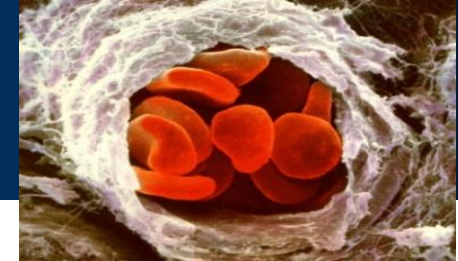
They can also be used to answer specific clinical questions and to improve aneurysm risk assessment

Simulation-assisted treatment planning and patient evaluation tools are becoming a reality

# RESEARCH TEAM

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Cecília NUNES



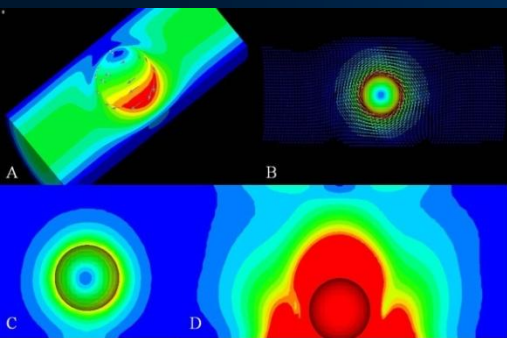
# COLLABORATIONS

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- IGC - Luís ROSÁRIO

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- Univ. Hassan II Ain-Chock , Casablanca - S. BOUJENA
- EPFL, Switzerland, Poli Milano - A QUARTERONI
- Czech Tech Univ, Prague, Czech Republic - T BODNÁR



# CURRENT PROJECTS

- *Multiscale Mathematical Modelling in Biomedicine*  
PTDC/ MAT / 68166/ 2006 [2007– 2010]
- *Cardiovascular Imaging Modeling and Simulation – SIMCARD*  
UTAustin/CA/0047/2008 [2009 - 2012]



**Eureka ! 4990 SIMCARD**

European Partnership: EPFL – Switzerland

**Alfio Quarteroni**

CMCS - Modelling and Scientific Computing Group

**THANK YOU !!!**