

Space-time DGM for time-dependent PDEs

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Lecture 6

- model heat equation,
- Let $\Omega \subset \mathbb{R}^d$, $\partial\Omega = \partial\Omega_D \cup \partial\Omega_N$, $\partial\Omega_D \cap \partial\Omega_N = \emptyset$, $Q_T \equiv \Omega \times (0, T)$, we seek $u : Q_T \rightarrow \mathbb{R}$ such that

Time-dependent heat equation

$$\frac{\partial u}{\partial t} - \varepsilon \Delta u = g \quad \text{in } Q_T, \quad (1)$$

$$u = u_D \quad \text{on } \partial\Omega_D, \quad t \in (0, T),$$

$$\nabla(u) \cdot \mathbf{n} = g_N \quad \text{on } \partial\Omega_N, \quad t \in (0, T),$$

$$u(x, 0) = u^0(x) \quad x \in \Omega,$$

where $\varepsilon > 0$.

Suitable assumptions on g , u_D , g_N and u^0 guarantee the existence and uniqueness of the weak solution.

Definition

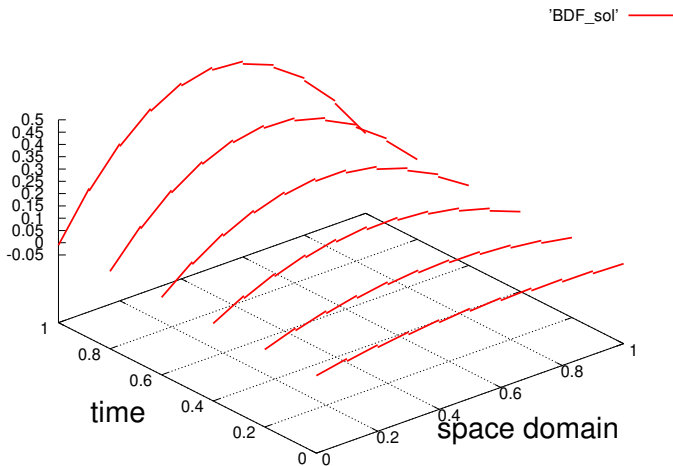
We say that u_h is a DGFE solution iff

- a) $u_h \in C^1(0, T; S_{hp}),$ (2)
- b) $(u_h'(t), \varphi_h) + A_h(u_h(t), \varphi_h) = l_h(\varphi_h) \quad \forall \varphi_h \in S_{hp}, t \in (0, T)$
- c) $u_h(0) = \Pi_{hp} u^0,$

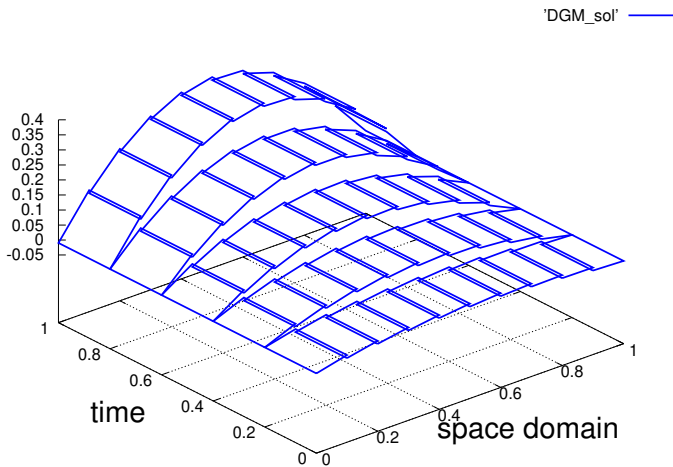
where $\Pi_{hp} u^0$ is a projection of IC in S_{hp}

- system of ODEs,
- number of equations = $\dim S_{hp}$
- (semi)-implicit ODE solver advantageous,

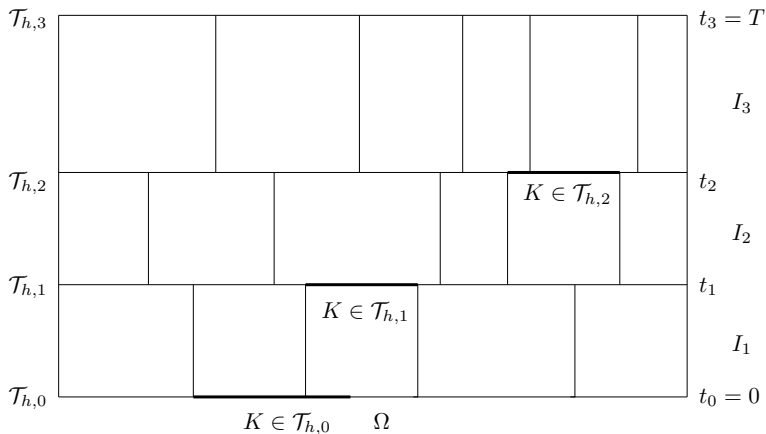
Approximation by BDF–DGM - 1D illustration



Approximation by space-time DGM - 1D illustration



Space-time discretization (1D illustration)



Space-time DG functional spaces

Time partition

- $0 = t_0 < \dots < t_r = T$
- $I_m = (t_{m-1}, t_m)$, $\tau_m = t_m - t_{m-1}$, $m = 1, \dots, r$.

Time limits

- let φ be a function defined on $\bigcup_{m=1}^r I_m$,
- $\varphi|_m^\pm := \lim_{t \rightarrow t_m^\pm} \varphi(t)$,
- $\{\varphi\}_m := \varphi|_m^+ - \varphi|_m^-$, $m = 1, \dots, r$.

DG space

$$S_{h,\tau}^{p,q} := \left\{ \varphi \in L^2(Q_T); \varphi(x, t)|_{I_m} = \sum_{i=0}^q t^i \varphi_{m,i}(x) \right. \quad (3)$$

$$\left. \text{with } \varphi_{m,i} \in S_{h,m}^p, i = 0, \dots, q, m = 1, \dots, r \right\}.$$

$$(u'_h(t), \varphi_h(t)) + A_h(u_h(t), \varphi_h(t)) = \ell_h(\varphi_h(t)), \quad \varphi_h \in S_{h,\tau}^{p,q}$$

integration over I_m

$$\int_{I_m} (u'_h(t), \varphi_h(t)) dt + \int_{I_m} (A_h(u_h(t), \varphi_h(t)) - \ell_h(\varphi_h)) dt = 0.$$

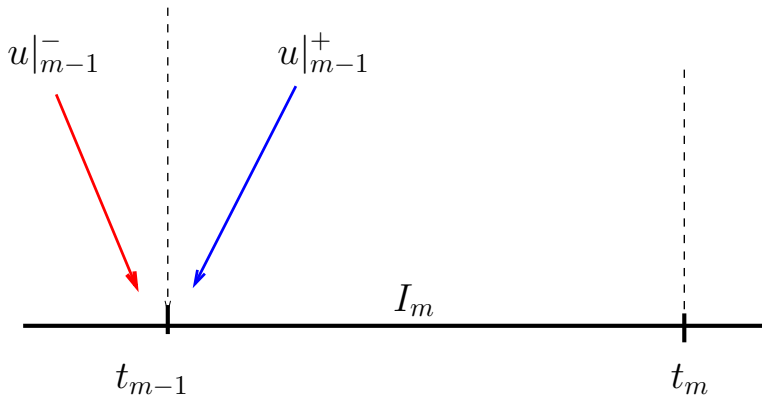
Manipulation with the first term (integration by parts):

$$\int_{I_m} (u', \varphi) dt = - \int_{I_m} (u, \varphi') dt + (u|_m^-, \varphi|_m^-) - (u|_{m-1}^+, \varphi|_{m-1}^+).$$

$$(u|_{m-1}^+, \varphi|_{m-1}^+) = (u|_{m-1}^-, \varphi|_{m-1}^+) \text{ (valid for } u \text{ being exact)}$$

reverse integration by parts:

$$\int_{I_m} (u', \varphi) dt = \int_{I_m} (u, \varphi') dt + (\{u\}_{m-1}, \varphi|_{m-1}^+)$$



Approximate STDG solution

We say that $u_h \in S_{h,\tau}^{p,q}$ is the STDG solution of (1) is

$$\int_{I_m} ((u'_h, \varphi) + A_h(u_h, \varphi) - \ell(\varphi)) dt + (\{u_h\}_{m-1}, \varphi|_{m-1}^+) = 0$$
$$\forall \varphi \in S_{h,\tau}^{p,q}, \quad m = 1, \dots, r, \quad \text{with } u_h|_0^- := \Pi_h u^0, \quad (4)$$

where $u'_h = \partial u_h / \partial t$.

- system of linear (nonlinear) algebraic equations
- # eqs. = $\# \mathcal{T}_h(p+1)(p+2)/2 (q+1)$ (in 2D)
- the mesh can be different on each time level t_m

Theorem

There exists a unique approximate solution

Proof: coercivity of the left-hand side can be shown.

A priori error estimate

$$\|(u - u_h)|_m\|_{L^2(\Omega)}^2 + \frac{\varepsilon}{2} \sum_{j=1}^m \int_{I_j} \|u - u_h\|_j^2 dt \quad (5)$$

$$\leq C\varepsilon \left(h^{2(\mu-1)} |u|_{C([0,T];H^\mu(\Omega))}^2 + \tau^{2(q+\gamma)} |u|_{H^{q+1}(0,T;H^1(\Omega))}^2 \right),$$

$\gamma = 0$ for a general u_D , $\gamma = 1$ for u_D polynomial w.r.t. t

A priori error estimate (2)

$$\sup_{t \in I_m} \|u(t) - u_h(t)\|_{L^2(\Omega)}^2 \quad (6)$$

$$\leq C \left(h^{2(\mu-1)} |u|_{C([0,T];H^\mu(\Omega))}^2 + \tau_m^{2(q+1)} |u|_{W^{q+1,\infty}(0,T;L^2(\Omega))}^2 \right),$$